I-2533CS-FD Series User Manual

Version 2.1.0, Apr. 2026

I-2533CS-FD /
I-2533CS-FD-60

I-2533CS-FD-A /
I-2533CS-FD-B

Service and usage information

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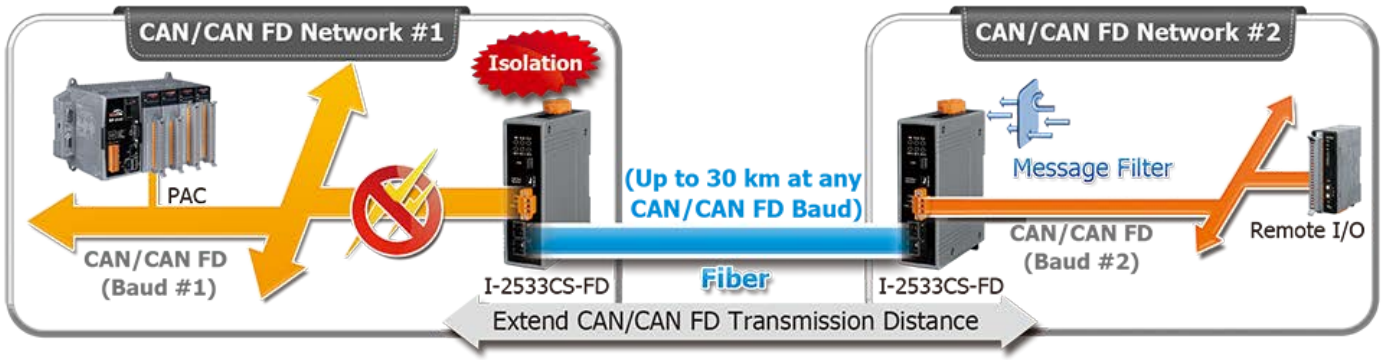
1. Introduction

The I-2533CS-FD series is a local CAN/CAN FD (CAN with Flexible Data-Rate) bridge used to establish a connection between two CAN bus systems via single mode fiber optic transmission medium. In order to solve the problem between CAN/CAN FD and fiber transmission medium, the I-2533CS-FD series is specially designed for converting the electrical CAN/CAN FD bus signal to fiber optic cables. Besides, I-2533CS-FD series has three more important features.

First, the transmission distance limitation of the CAN bus system will not affected due to the different CAN/CAN FD baud rate. It means that the total CAN/CAN FD bus working distance can be extended. Second, the bus error on one CAN/CAN FD network will not affect the operation of another CAN/CAN FD network. Finally, the two CAN/CAN FD network can communication with each other by using different CAN/CAN FD baud rate for highly flexibility.



The I-2533CS-FD series is designed for single mode fiber, and allow to extern CAN/CAN FD bus to maximum 30 km. Besides, I-2533CS-FD series provides the group function, which is the basic message router. Users can decide the CAN/CAN FD message flows between several CAN/CAN FD bus systems. I-2533CS-FD series also provides the utility tool for user-defined baud rate and filter configuration. By using this tool, it is allowed to have user-defined baud rate and CAN/CAN FD message filter. When users use the I-2533CS-FD series on two CAN/CAN FD network with different CAN baud rate, it may be useful to reduce the bus loading of the network which has low baud rate.

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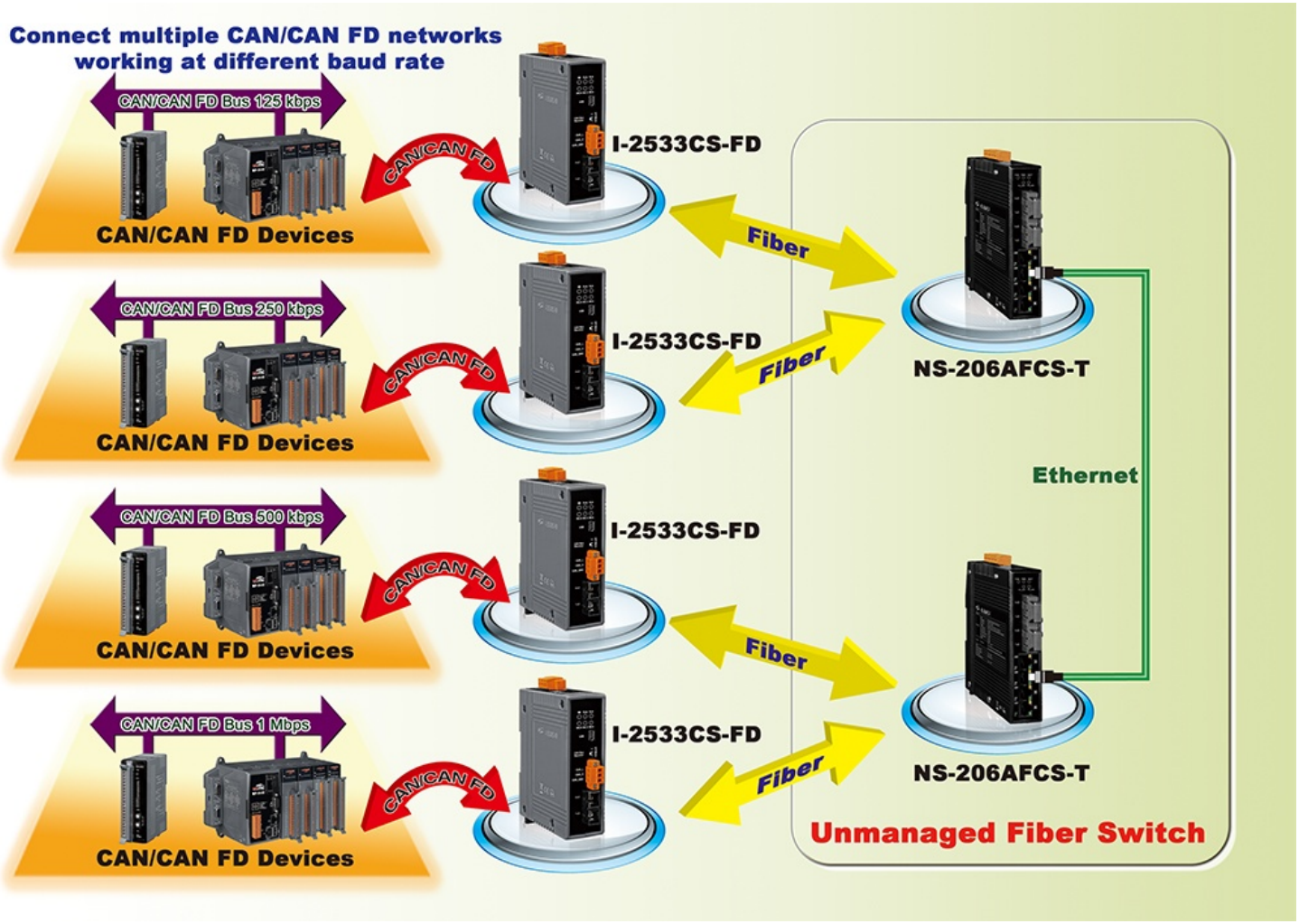

RAW Data to CAN/CAN FD communication

TCP/UDP to CAN/CAN FD transparent communication
(Firmware v2.00 support)

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1.1. Specifications

Model Name	I-2533CS-FD	I-2533CS-FD-60	I-2533CS-FD-A / I-2533CS-FD-B
CAN Interface			
Channel Number	1		
Connector	3-pin terminal-block connector		
Transmission Speed	CAN bit rates: 10 ~ 1000 kbps, CAN FD bit rates for data field: 100 ~ 10000 kbps		
Terminal Resistor	DIP switch for the 120 Ω terminal resistor		
Isolation	3000 VDC for DC-to-DC, 2500 Vrms for photocoupler		
Specification	ISO 11898-2, CAN 2.0 A/B and FD		
CAN Filter Configuration	Selectable via Utility tool		
Receive Buffer	128 data frames		
Fiber Interface			
Type	SC type ; Single mode ; 100 Base-FX		
Wave Length (nm)	1310		TX: 1310, RX: 1550 ➔I-2533CS-FD-A TX: 1550, RX: 1310 ➔I-2533CS-FD-B
Fiber Cable (μm)	8.3/125, 8.7/125, 9/125 or 10/125		
Transmission Distance (km)	30	60	15
Min. TX Output (dBm)	-15	-5	-14
Max. TX Output (dBm)	-8	0	-8
Max. RX Sensitivity (dBm)	-34	-35	-31
Max. RX Overload (dBm)	-5	-5	0
Budget (dBm)	19	30	17
USB Interface			
Connector	1 x USB (Mini-B)		
Compatibility	USB 2.0 High Speed (480Mbps)		
Software Driver	Built-in Windows 7/8.1/10		
LED			

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Round LED	PWR, FB_Ack, FB_Err, CAN_Err, CAN_Tx and CAN_Rx LEDs
Power	
Power supply	Unregulated +10 ~ +30 V_{DC}
Protection	Power reverse polarity protection, Over-voltage brown-out protection
Power Consumption	0.125A @ 24V_{DC}
Mechanism	
Installation	DIN-Rail
Dimensions	33.0 mm x 127 mm x 101 mm (W x L x H)
Environment	
Operating Temp.	-25 ~ 75 ℃
Storage Temp.	-30 ~ 80 ℃
Humidity	10 ~ 90% RH, non-condensing

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1.2. Features

Hardware

- Compatible with the ISO 11898-2 standard
- Compatible with CAN specification 2.0 A/B and FD
- CAN FD support for ISO and Non-ISO (Bosch) standards switchable
- CAN FD bit rates for data field from 100 kbps to 10000 kbps
- CAN bit rates from 10 kbps to 1000 kbps
- Fiber broken line detection
- Built-in switchable 120 ohm terminal resistor for CAN Bus
- Dip switch for CAN/CAN FD baud rate configuration

Software

- CAN Bus ID filter
- Basic CAN message routing function via Group ID settings.
- TCP/UDP to CAN transparent communication (Firmware v2.00 support)
- UDP responder for device discovery (Firmware v2.00 support)
- Static IP or DHCP network configuration (Firmware v2.00 support)

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2. Technical data

2.1. Block Diagram

The following figure is the block diagram illustrating the functions of the I-2533CS-FD series.

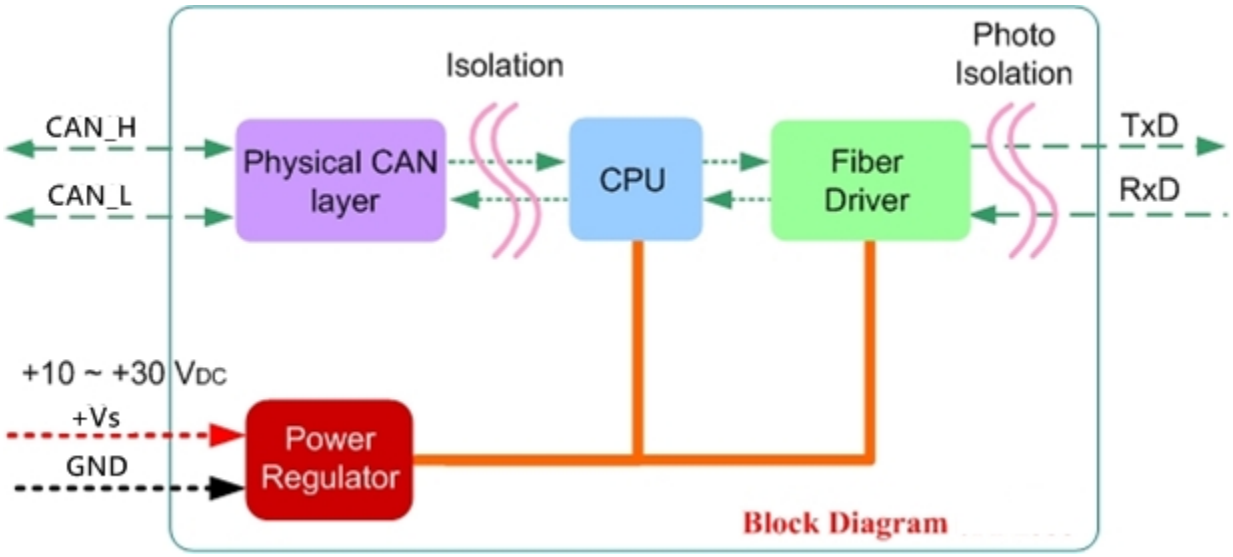

Figure 2-1-1 Block Diagram of I-2533CS-FD series

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2.2. Appearance

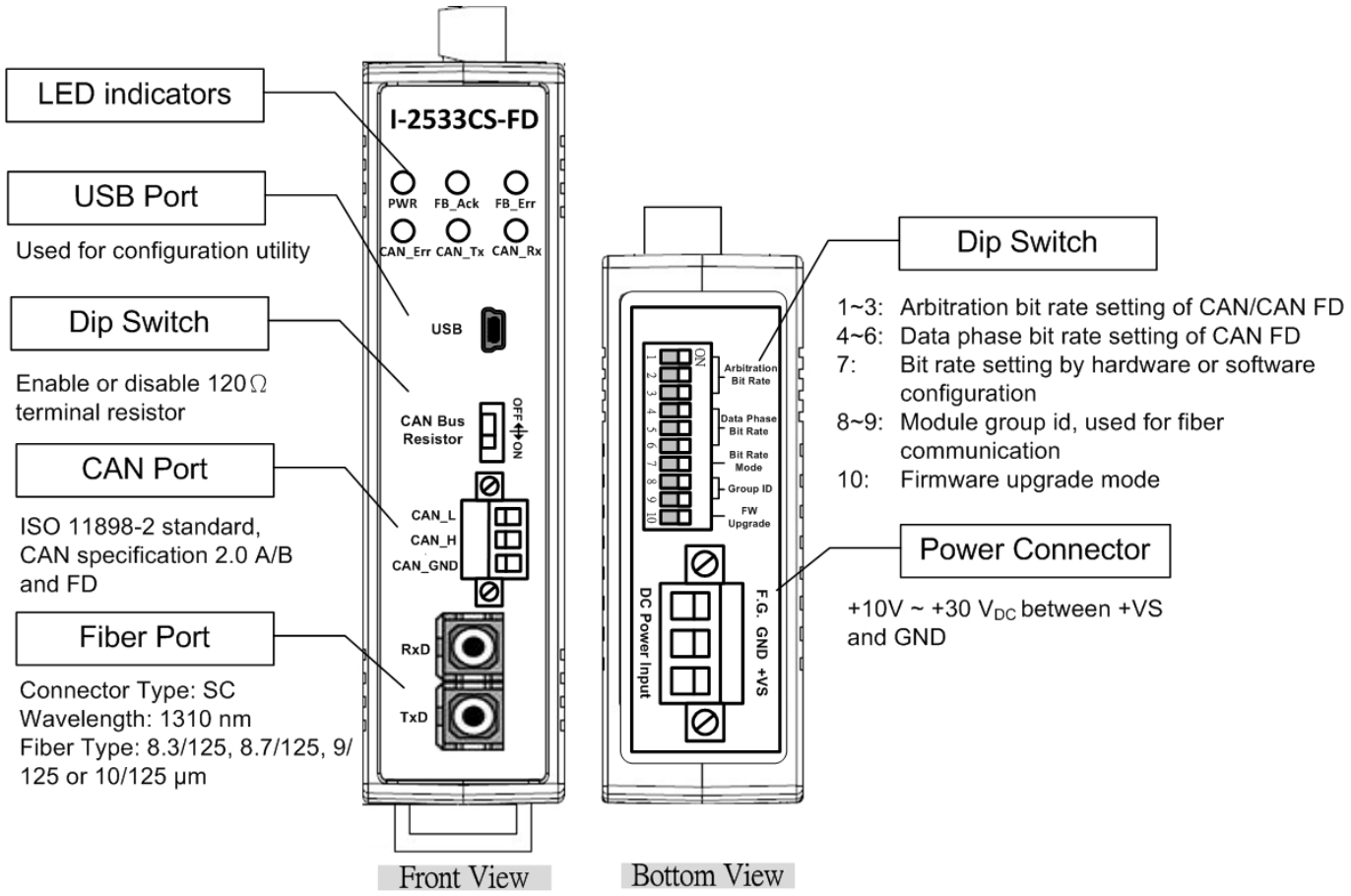

Figure 2-2-1 Appearance of I-2533CS-FD and I-2533CS-FD-60

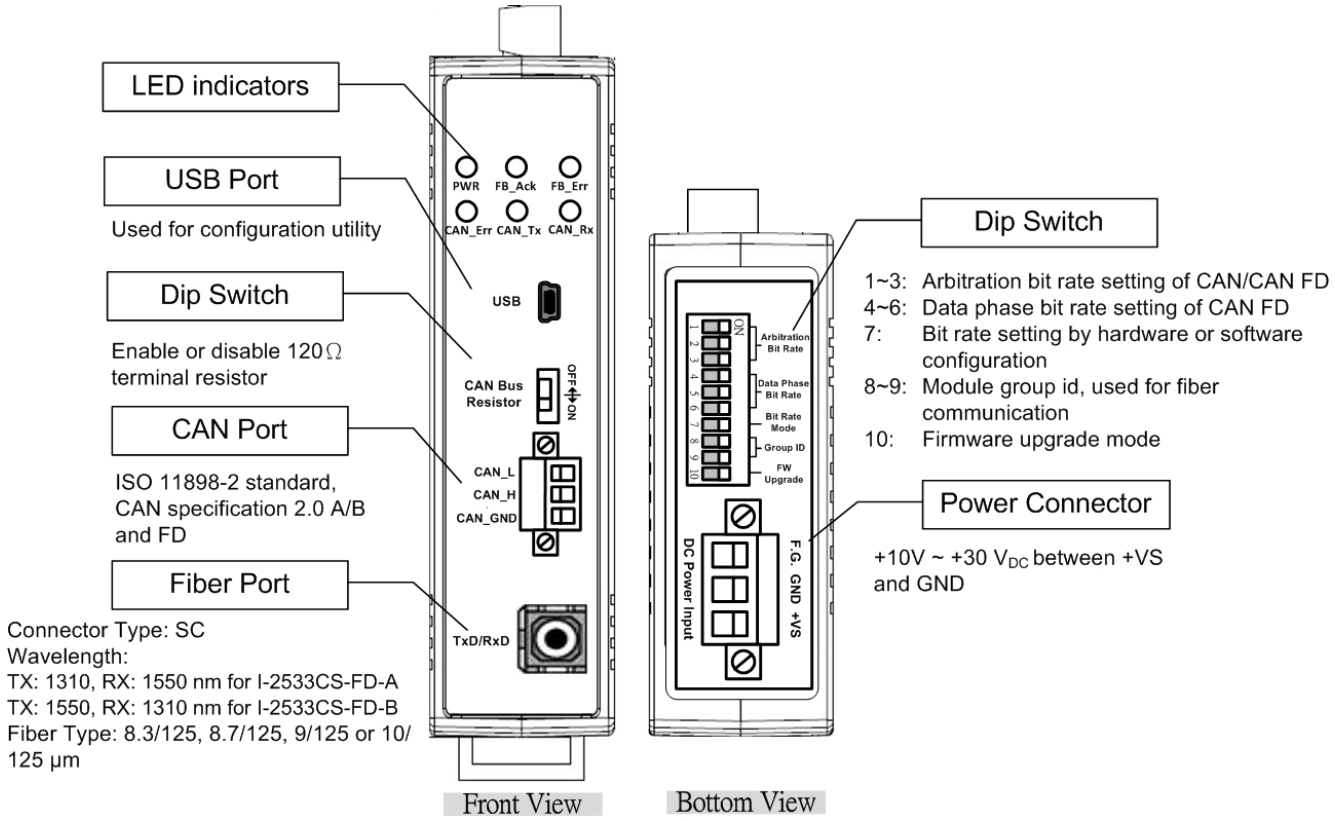

Figure 2-2-2 Appearance of I-2533CS-FD-A and I-2533CS-FD-B

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2.3. Pin Assignment

The pin assignments of USB, CAN port, fiber port and power connector of I-2533CS-FD series is shown in the following tables.

Table 2-3-1 Pin Assignment

Port	Name	Description
USB	USB	Used for configuration utility
CAN	CAN_L	CAN_Low, signal line of CAN port.
	CAN_H	CAN_High, signal line of CAN port.
	CAN_GND	CAN_Ground, ground voltage level of CAN port.
Fiber	TxD	Transmit optic data.
	RxD	Receive optic data.
Power	+Vs	Voltage Source Input. $+10V_{DC}$ ~ $+30V_{DC}$.
	GND	Power Ground.
	F.G.	Frame Ground.

Sometimes, the CAN_GND voltage level of different CAN devices on a CAN bus system are not equal. In this case, it could cause some problems and derogate the system stability. There is one way to relieve this situation; users can connect the CAN_GND of different CAN devices with each other to balance the voltage level of CAN_GND.

Electronic circuits are always influenced by different levels of Electro-Static Discharge (ESD), which become worse in a continental climate area. F.G. provides a path for conducting the ESD to the earth ground. Therefore, connecting the F.G correctly can enhance the capability of the ESD protection and improve the module's reliability.

Wiring of CAN_GND and F.G. is not necessary; users can modify the configuration of wiring according to real applications.

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2.4. 10-pin Dip Switch

When users would like to set the CAN/CAN FD baud rate, module's group id or update the firmware of the I-2533CS-FD series, Users can use the 10-pin dip switch on the upper of the power connector to achieve these purposes. Users can find it on the top of the power connector.

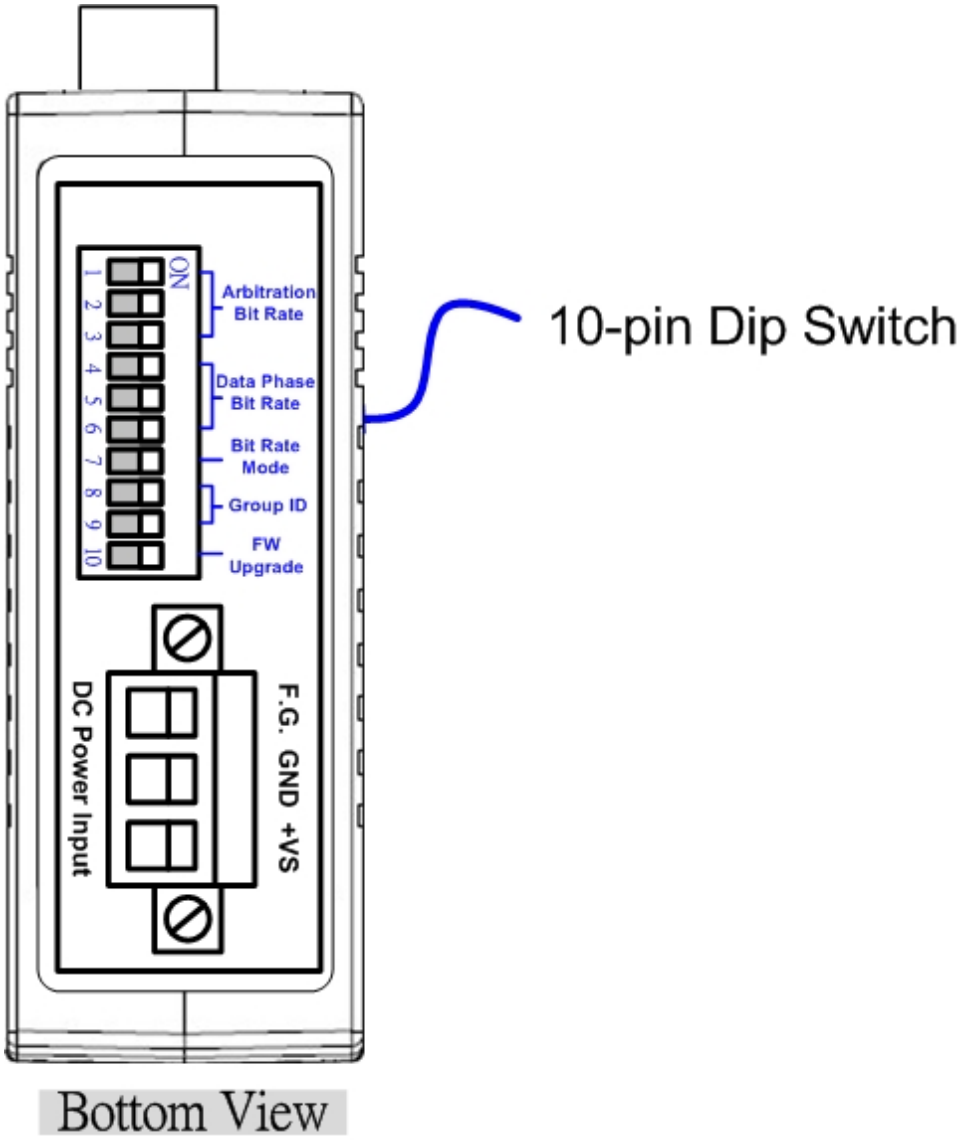

Figure 2-4-1 Location of 10-pin Dip Switch

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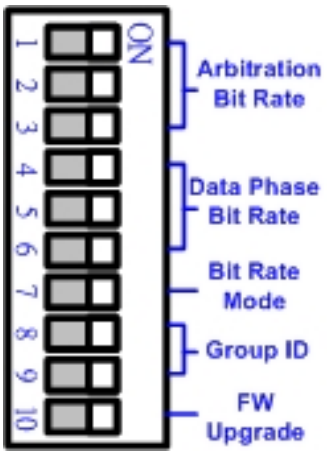
About the function of the 10-pin dip switch, they are described on the following table.

Table 2-4-1 Description of 10-pin Dip Switch

<table>
<tr><th>10-pin dip switch</th><th>Pin</th><th>Switch Function</th><th>Description</th></tr>
<tr><td rowspan="4"> 

■ : ON
□ : OFF</td><td>1 ~ 3</td><td>Arbitration Bit Rate of CAN/CAN FD message</td><td><table>
<tr><th>Bit Rate (kbps)</th><th>1</th><th>2</th><th>3</th></tr>
<tr><td>10</td><td>□</td><td>□</td><td>□</td></tr>
<tr><td>20</td><td>■</td><td>□</td><td>□</td></tr>
<tr><td>50</td><td>□</td><td>■</td><td>□</td></tr>
<tr><td>125</td><td>■</td><td>■</td><td>□</td></tr>
<tr><td>250</td><td>□</td><td>□</td><td>■</td></tr>
<tr><td>500</td><td>■</td><td>□</td><td>■</td></tr>
<tr><td>800</td><td>□</td><td>■</td><td>■</td></tr>
<tr><td>1000</td><td>■</td><td>■</td><td>■</td></tr>
</table></td></tr>
<tr><td>4 ~ 6</td><td>Data Phase Bit Rate of CAN FD message</td><td><table>
<tr><th>Bit Rate (kbps)</th><th>4</th><th>5</th><th>6</th></tr>
<tr><td>100</td><td>□</td><td>□</td><td>□</td></tr>
<tr><td>125</td><td>■</td><td>□</td><td>□</td></tr>
<tr><td>250</td><td>□</td><td>■</td><td>□</td></tr>
<tr><td>500</td><td>■</td><td>■</td><td>□</td></tr>
<tr><td>800</td><td>□</td><td>□</td><td>■</td></tr>
<tr><td>1000</td><td>■</td><td>□</td><td>■</td></tr>
<tr><td>2000</td><td>□</td><td>■</td><td>■</td></tr>
<tr><td>3000</td><td>■</td><td>■</td><td>■</td></tr>
</table></td></tr>
<tr><td>7</td><td>Bit Rate Mode</td><td>ON:
Use Arbitration/ Data Phase bit rate setting by Utility configuration
OFF:
Use Arbitration/ Data Phase bit rate setting by dip switch setting</td></tr>
<tr><td>8 ~ 9</td><td>Module’s group ID</td><td><table>
<tr><th>Group ID value</th><th>8</th><th>9</th></tr>
<tr><td>00</td><td>□</td><td>□</td></tr>
<tr><td>01</td><td>■</td><td>□</td></tr>
<tr><td>02</td><td>□</td><td>■</td></tr>
<tr><td>03</td><td>■</td><td>■</td></tr>
</table></td></tr>
<tr><td>10</td><td>Firmware upgrade mode</td><td>ON:
Into firmware upgrade mode.
OFF:
Into normal operating mode.</td></tr>
</table>

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2.5. LED Indicator

There are 6 LEDs on the I-2533CS-FD series. One for power indication, two for fiber indication and three for CAN bus indication. The LED assignment and description are shown as follows.

Figure 2-5-1 LED Assignment of I-2533CS-FD series

Table 2-5-1 LED Description

LED Name	Color	Description
PWR	Red	When power on this LED is turned on.
FB_Ack	Green	When the I-2533CS-FD series sends/receives one message to/from the fiber, this LED flashes once.
FB_Err	Orange	If the I-2533CS-FD series detects the RXD line of the fiber is off, this LED is always on.
CAN_Err	Red	1. If the I-2533CS-FD series detects the bus-off status on the CAN bus, this LED is always on. 2. If the CAN data buffer is full, this LED flashes once per second. 3. If the I-2533CS-FD series can't send CAN/CAN FD messages successfully because the bus connector is off or some errors happen, this LED flashes five times per second.
CAN_Tx	Green	When the I-2533CS-FD series transmits one CAN/CAN FD message to CAN bus, this LED flashes once.
CAN_Rx	Green	When the I-2533CS-FD series receives one CAN/CAN FD message from CAN bus, this LED flashes once.

NOTE:
In "Firmware Upgrade Mode", the CAN_Err, CAN_Tx, CAN_Rx and FB_Err LEDs will flash per 500 milliseconds.

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2.6. Terminal Resistor Setup

In order to minimize the reflection effects on the CAN bus line, the CAN bus line has to be terminated at both ends by two terminal resistors as in the following figure. According to the ISO 11898-2 spec, each terminal resistor is 120Ω (or between 108Ω~132Ω). The bus topology and the positions of these terminal resistors are shown as following figure.

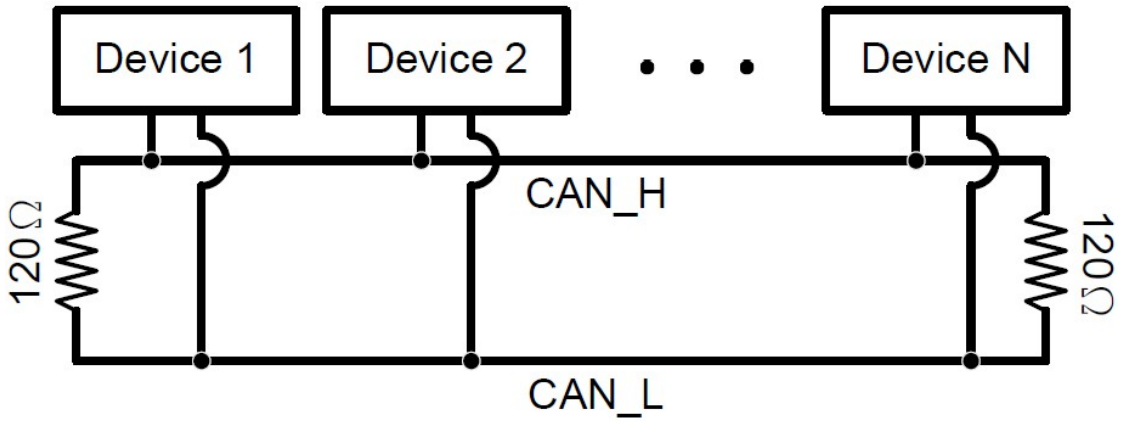

Figure 2-6-1 CAN bus network topology

Each I-2533CS-FD series includes one build-in 120Ω terminal resistor, users can decide to enable it or not. The DIP switch for terminal resistor is on the upper of the CAN connector.

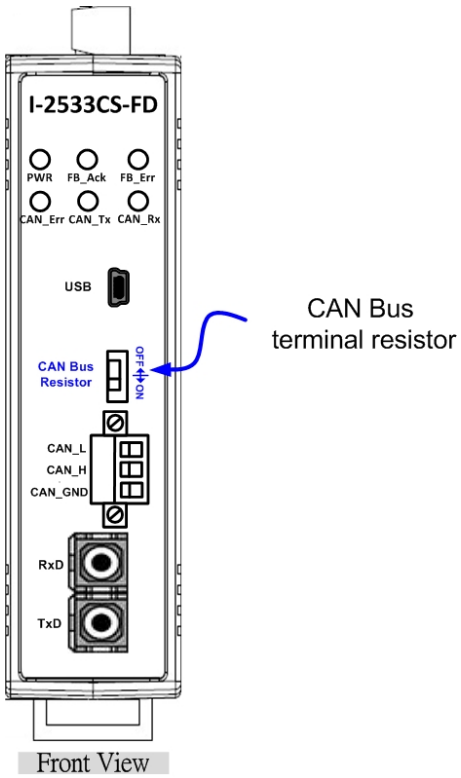

Figure 2-6-2 Location of Terminal resistor DIP Switch

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The following DIP switch statuses present the condition if the terminal resistor is active (default) or inactive.

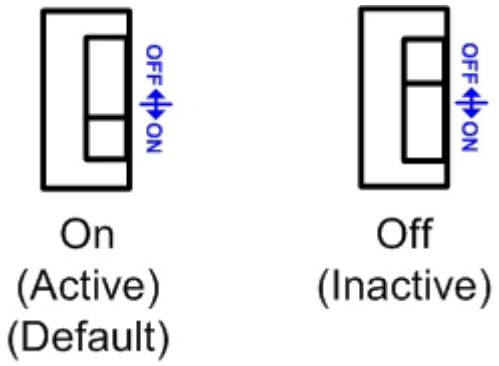

Figure 2-6-3 Adjustment of Terminal Resistance

Generally, if your application is as follows, we recommend you to enable the terminal resistor.

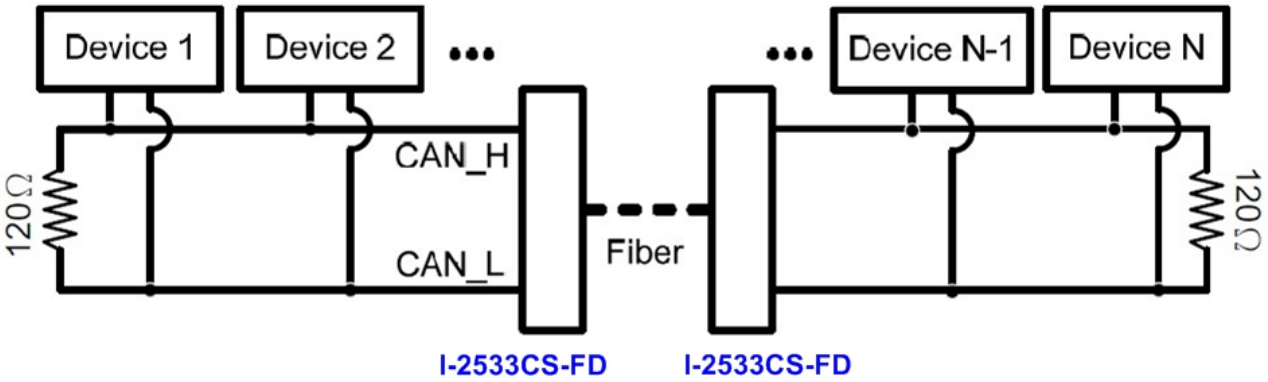

Figure 2-6-4 Application 1

If your application is like the structure as follows, the terminal resistor is not needed.

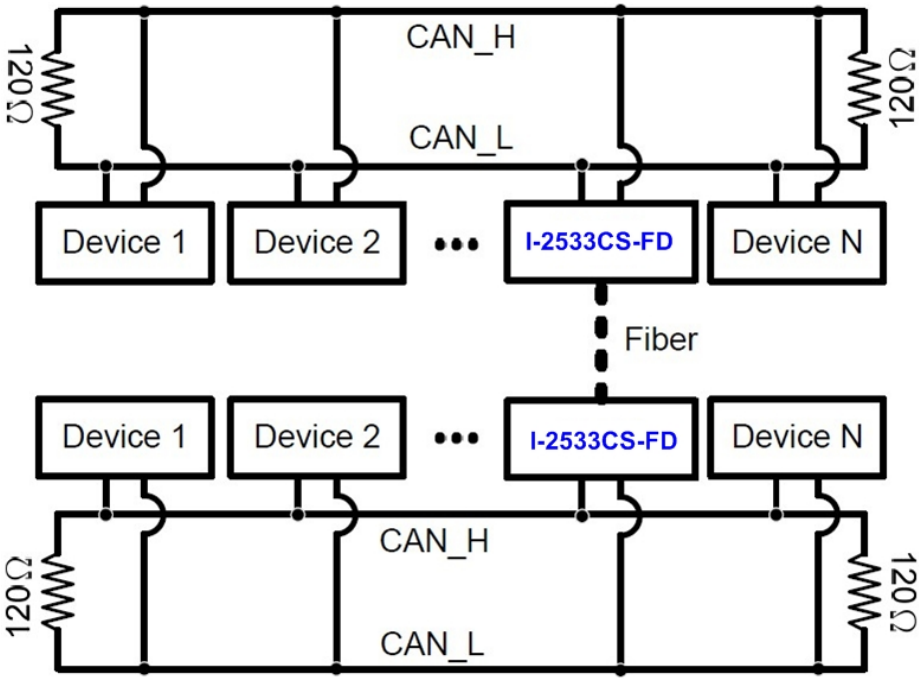

Figure 2-6-5 Application 2

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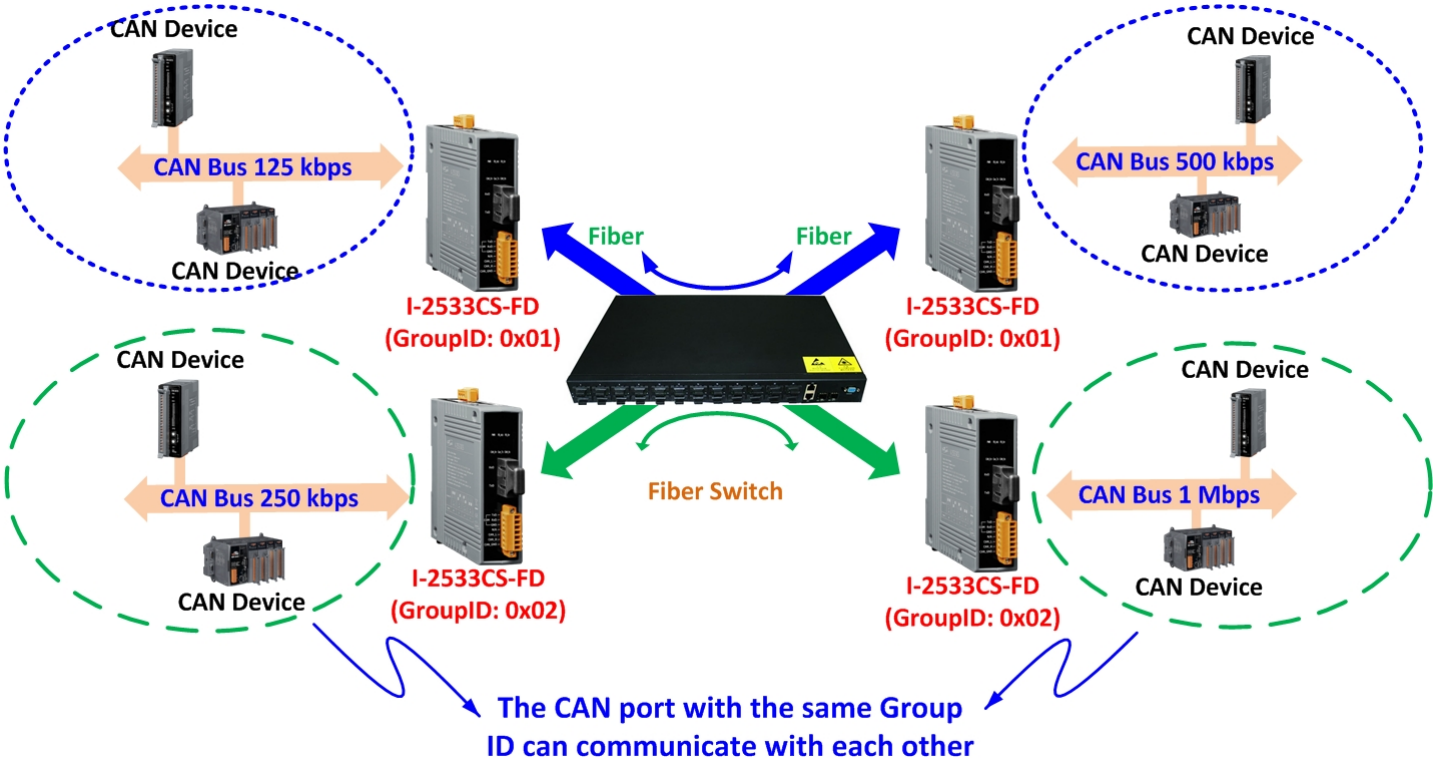
2.7. Module Group ID

When the communication method of the I-2533CS-FD series is set to RAW Data Mode, the CAN port with the same “Group ID” setting can communicate with each other via fiber optics. This setting is used for I-2533CS-FD series to communicate with the others modules on star topology application.



Users can decide the value from 0 to 3 via pin 8 ~ 9 on 10-pin dip switch. The dip switch for “Group ID” is over the power connector.

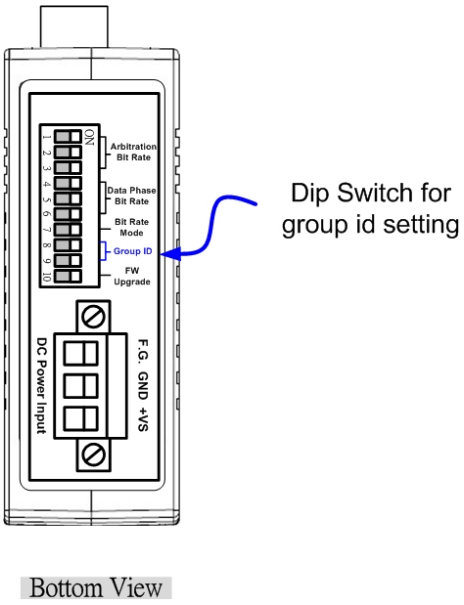


Figure 2-7-1 Location of Group ID DIP Switch

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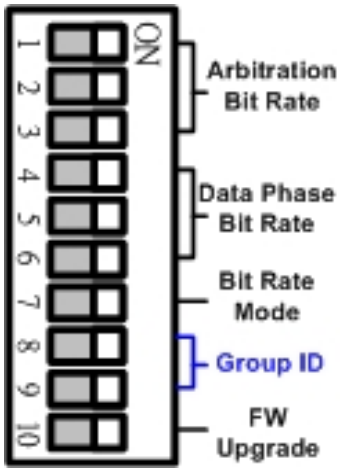
The following DIP switch statuses present the “Module Group ID” value.

Table 2-7-1 Group ID Description

<table>
<tr><th>10-pin dip switch</th><th>Pin</th><th>Switch Function</th><th>Description</th></tr>
<tr>
<td> 

■ : ON
□ : OFF</td>
<td>8 ~ 9</td>
<td>Module’s group ID</td>
<td>
<table>
<tr><th>Group ID value</th><th>8</th><th>9</th></tr>
<tr><td>00</td><td>□</td><td>□</td></tr>
<tr><td>01</td><td>■</td><td>□</td></tr>
<tr><td>02</td><td>□</td><td>■</td></tr>
<tr><td>03</td><td>■</td><td>■</td></tr>
</table>
</td>
</tr>
</table>

The following “Module Group ID” values of device A and B present these ID are in the same group which can communicate with each other.

Table 2-7-2 Group of “Module Group ID”

Items	Device A Group ID value	Device B Group ID value
1	**00**	**00**
2	**01**	**01 or 03**
3	**02**	**02 or 03**
4	**03**	**01 or 02 or 03**

For example, there are three CAN networks, Network A, Network B and Network C, and each of them uses one I-2533CS-FD series. The Group IDs of the I-2533CS-FD series are 1, 2, and 3 respectively. The Network A can exchange the data with Network C because the Group IDs of the I-2533CS-FD series are in the same group (the second rule in the above table). The Network B can exchange the data with Network C, which follows the third rule in the above table. The Network A can’t connect with the Network B because these two I-2533CS-FD series are not in the same group.

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2.8. Wire Connection

The wire connection of the I-2533CS-FD is displayed below.

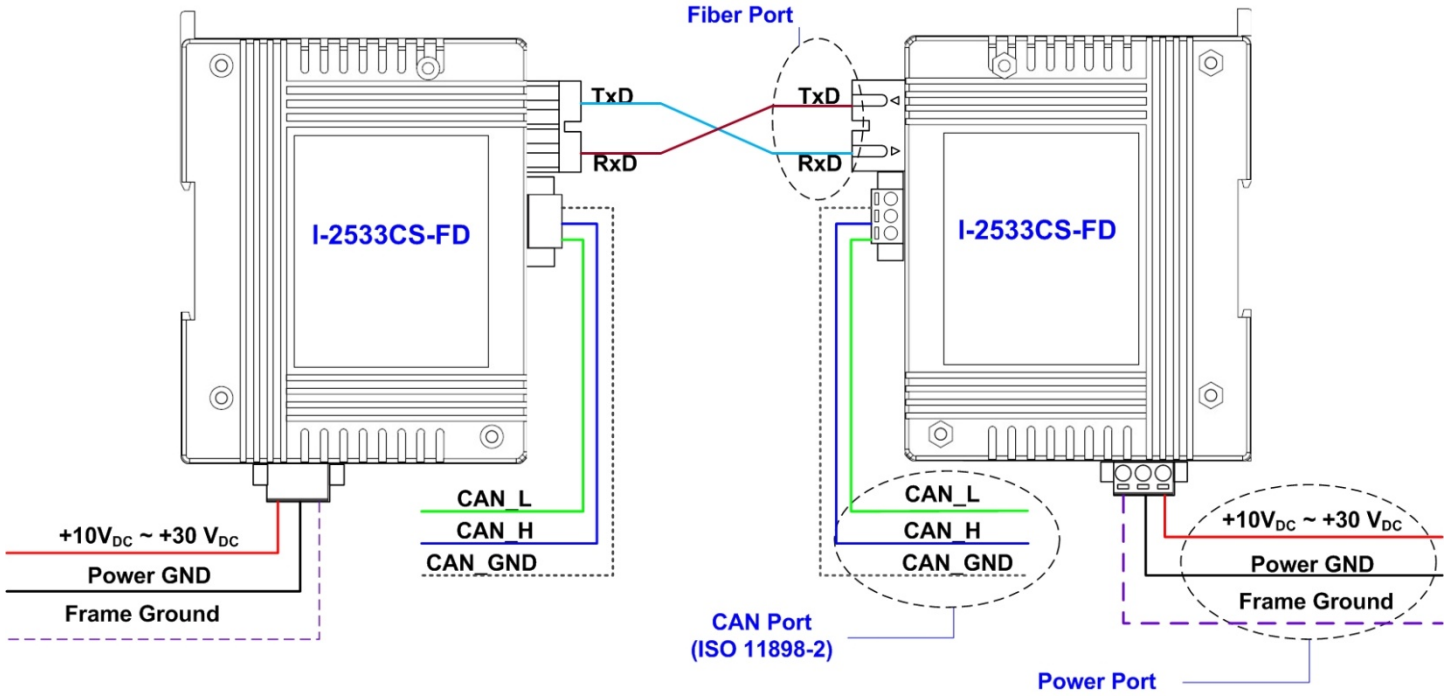

Figure 2-8-1 Wire Connection for I-2533CS-FD and I-2533CS-FD-60

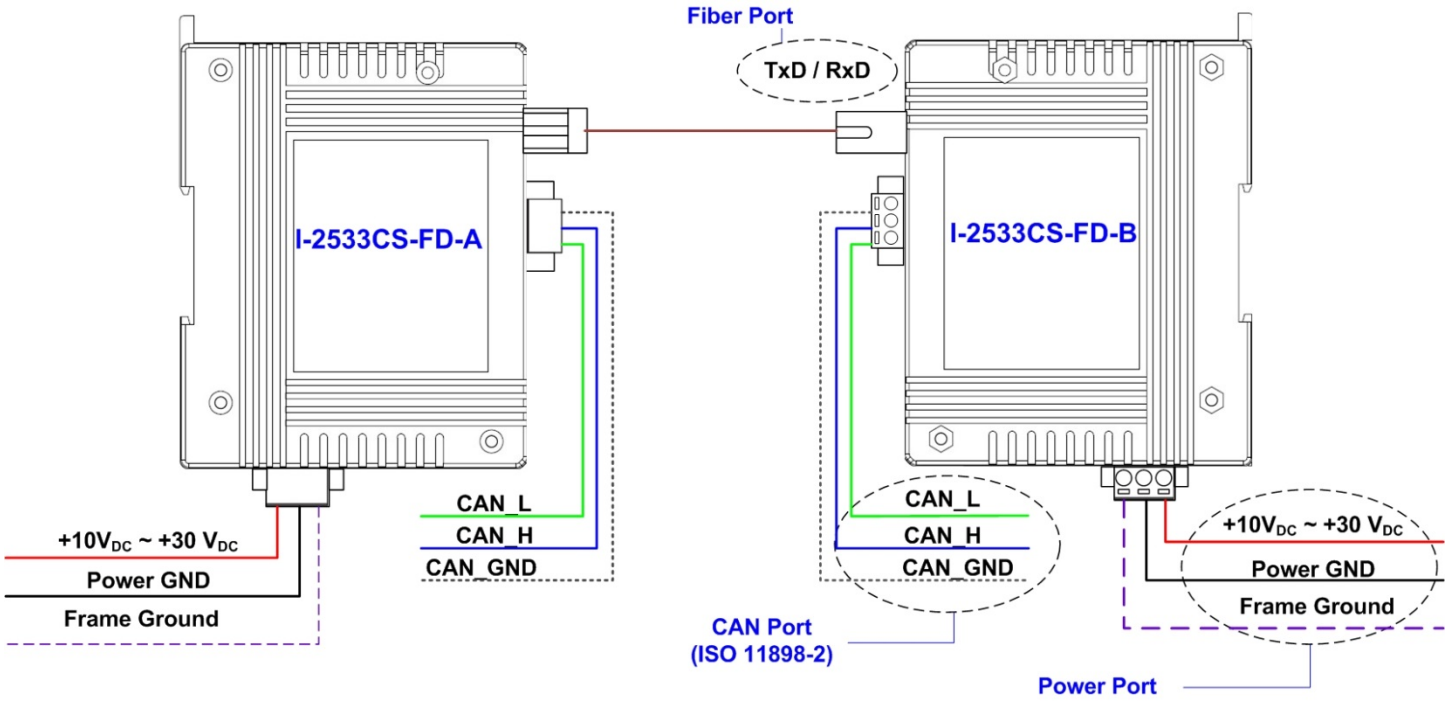

Figure 2-8-2 Wire Connection for I-2533CS-A and I-2533CS-FD-B

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3. Network Deployment

3.1. Driving Capability

Before introducing the driving capability of the I-2533CS-FD series, some characteristics of copper cable must be assumed. The AC parameters are 120Ω impedance and 5ms/, line delay, and the DC parameter follows the table show below.

Table 3-1-1 Recommended DC parameter for CAN Bus Line

Wire Cross-Section [mm^2]	Resistance [Ω/km]
~0.25 (AWG23)	< 90
~0.5 (AWG20)	< 50
~0.8 (AWG18)	< 33
~1.3 (AWG16)	< 20

Under the condition described above, users can refer to the following table to know the maximum node number in each segment following ISO 11898-2 and the maximum segment length when using different type of wire.

Table 3-1-2 Driving Capability

Wire Cross-Section [mm^2]	The maximum segment length [m] under the case of specific node number in this segment			
	16 Nodes	32 Nodes	64 Nodes	100 Nodes
~0.25 (AWG23)	< 220	< 200	< 170	< 150
~0.5 (AWG20)	< 390	< 360	< 310	< 270
~0.8 (AWG18)	< 590	< 550	< 470	< 410
~1.3 (AWG16)	< 980	< 900	< 780	< 670

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3.2. Fiber Selection & Fiber Length

The specification of fiber cable used to connect the I-2533CS-FD series is shown as following table.

Table 3-2-1 Specification of Fiber

Type	Diameter [μm] (Core/Cladding)	Operating Wavelength [nm]
Single mode	8.3/125, 8.7/125, 9/125 or 10/125	1310 or 1550

The I-2533CS-FD series allows maximum 30km fiber length for each kind of CAN baud theoretically. Although the maximum fiber length has no relationship with the CAN baud rate, but some fiber attributions, such as attenuation, still influence it. Higher attenuation of fiber will reduce the transmission distance. User can use following table to know the relationship between those two.

Table 3-2-2 The relationship between CAN baud rate and theoretical Fiber length

Module Name	Arbitration bit rate (bps)	Data Phase bit rate (bps)	Allowed Fiber length [km]
I-2533CS-FD	1 M ~ 10 k	100 k ~ 10M	30
I-2533CS-FD-60			60
I-2533CS-FD-A / I-2533CS-FD-B			15

Table 3-2-3 Fiber Attenuation & Fiber Length

Module Name	Fiber Attenuation [dB/km]	Allowed Fiber length [km]
I-2533CS-FD	0.4	30
	> 0.4	< 30
I-2533CS-FD-60	0.4	60
	> 0.4	< 60
I-2533CS-FD-A / I-2533CS-FD-B	0.4	15
	> 0.4	< 15

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4. Software Utility

When users want to use user-defined CAN/CAN FD baud rate and CAN/CAN FD message filter on the I-2533CS-FD series, the I-2533CS-FD Utility tool may be needed.

4.1. Install the I-2533CS-FD Utility

Step 1: Get the I-2533CS-FD Utility

The software is located at:
http://www.icpdas.com/en/download/show.php?num=2454&model=I-2533CS-FD

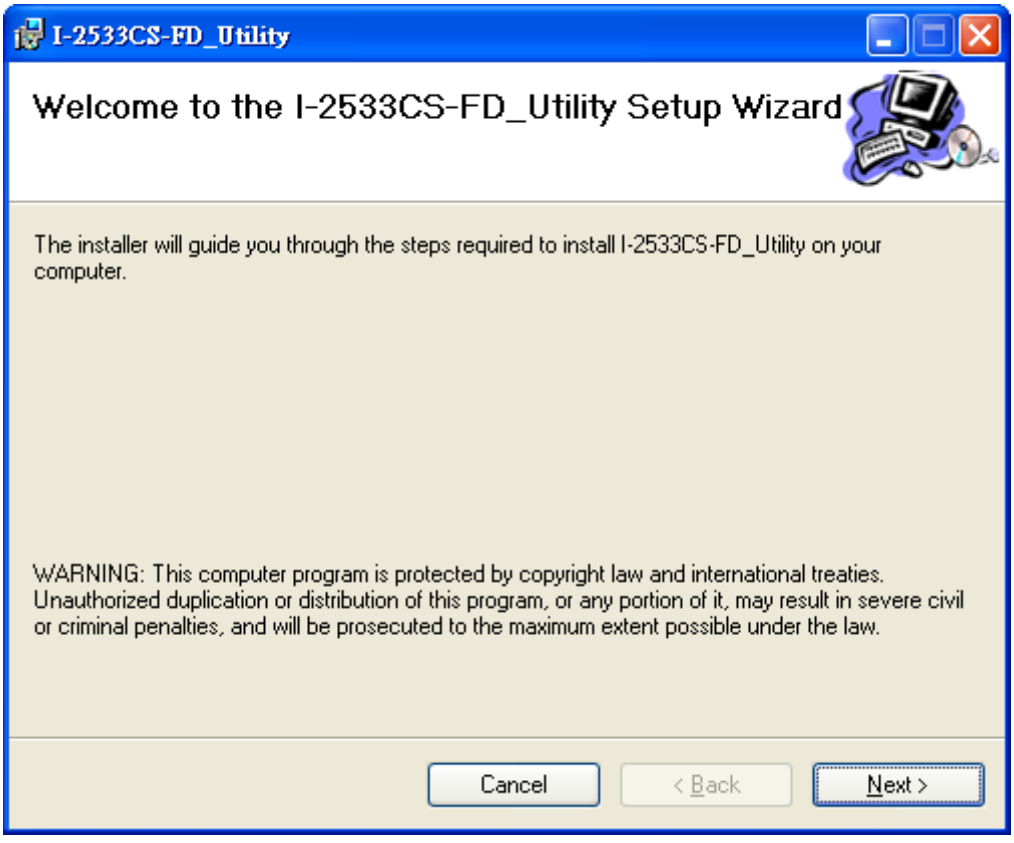
Step 2: Install .NET Framework 3.5 component

The I-2533CS-FD Utility tool requires the .NET Framework 3.5 components. After executing the “Setup.msi” file, it will start to install .NET Framework 3.5 components.

Step 3: Install Utility tool

After installing the .Net Framework components, the software will continue to install the Utility tool.

1. Click the “Next” button to continue.



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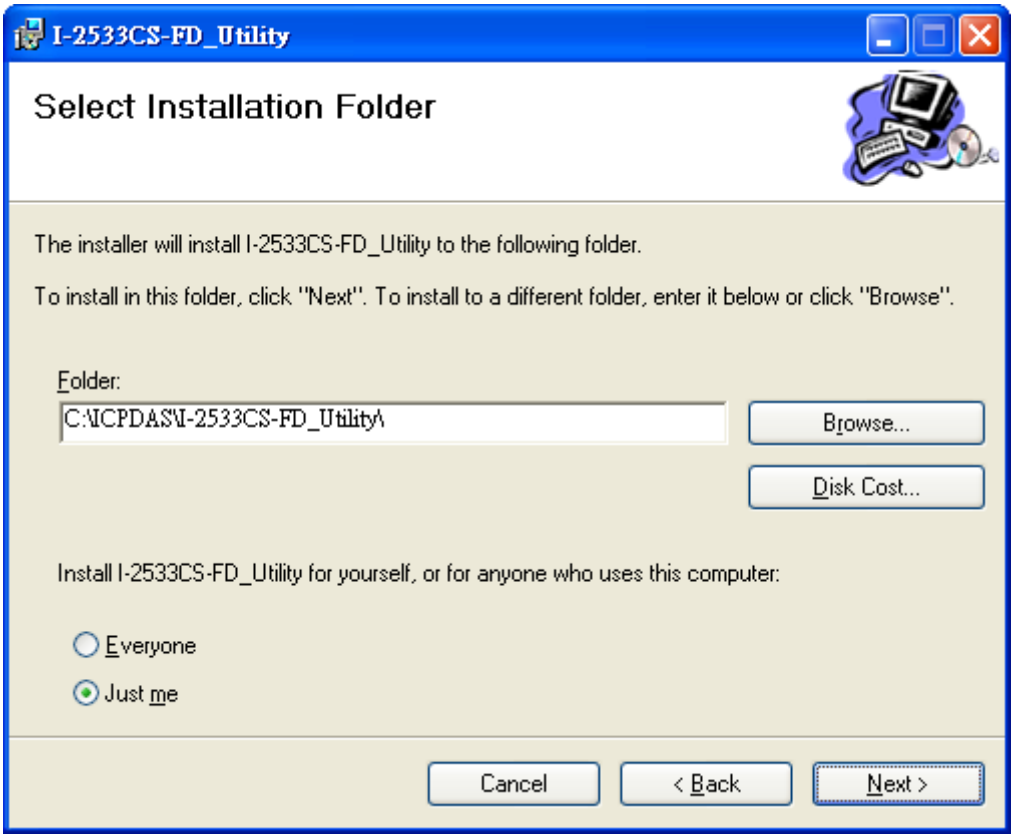
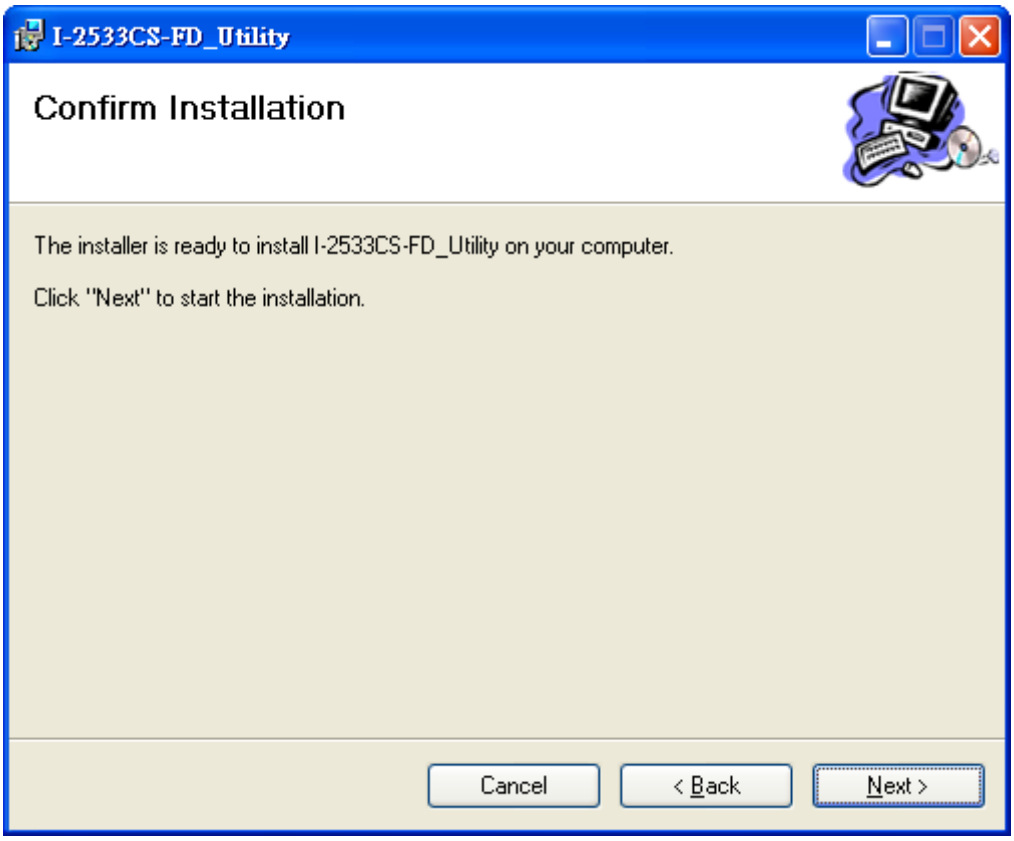
2. Select the installation path of the I-2533CS-FD Utility and click the “Next” button.



3. Confirm the installation. Click the “Next” button to start the installation



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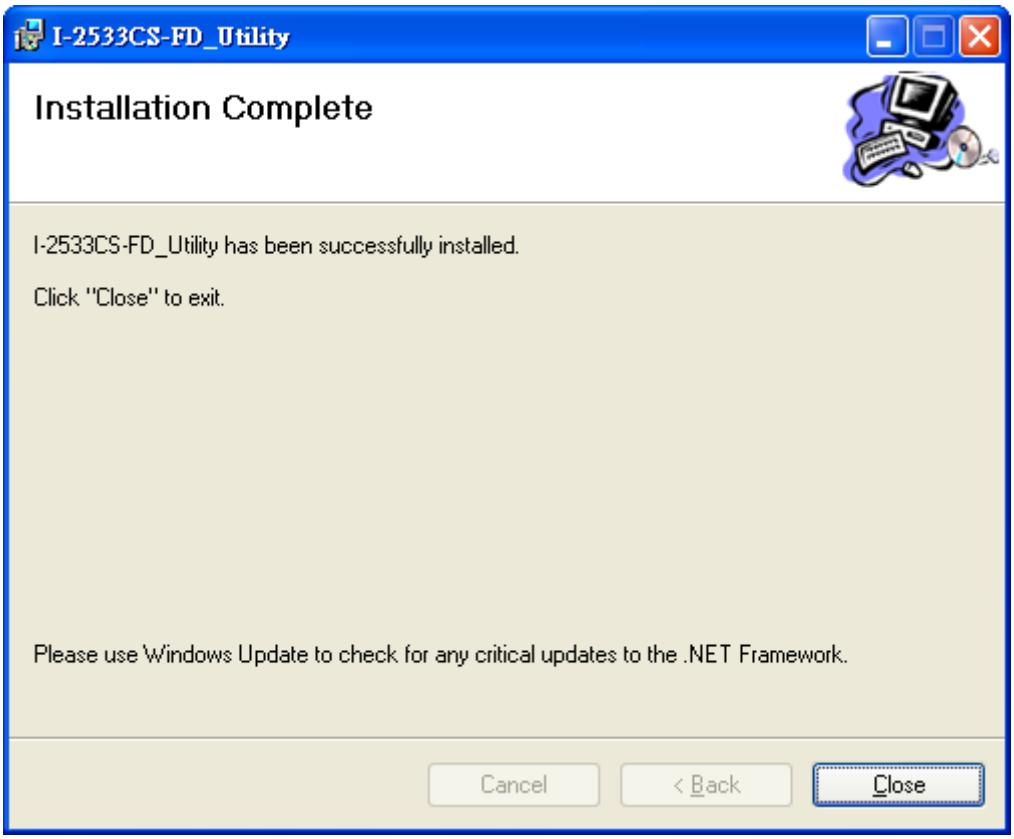
4. Installation complete. Click the “Close” button to exit



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4.2. Setting up the I-2533CS-FD series

After installing the utility tool, please follow the following steps to set up the communication between the Utility and the I-2533CS-FD series. Here is the example for the I-2533CS-FD series configuration.

Step 1: Connect the PC available USB port with the USB port of the I-2533CS-FD series. Users can find the communication cable (CA-USB10) in the product box.

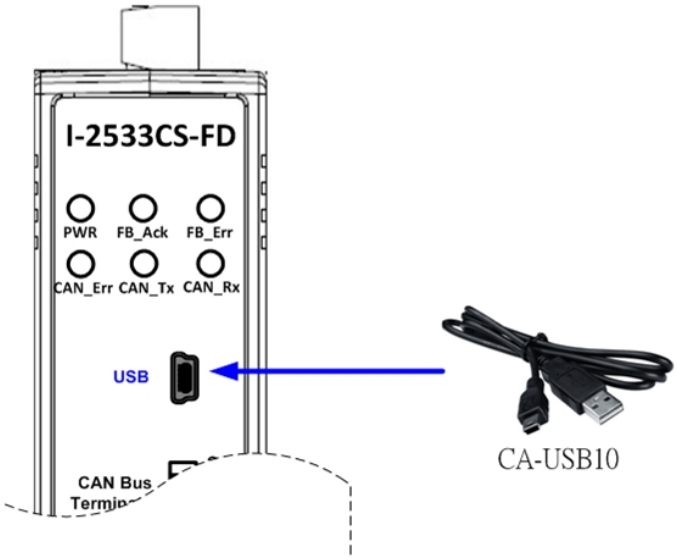

Figure 4-2-1 Wire connection of the USB port

Step 2: Execute the I-2533CS-FD Utility tool.

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4.3. Start to use I-2533CS-FD Utility tool

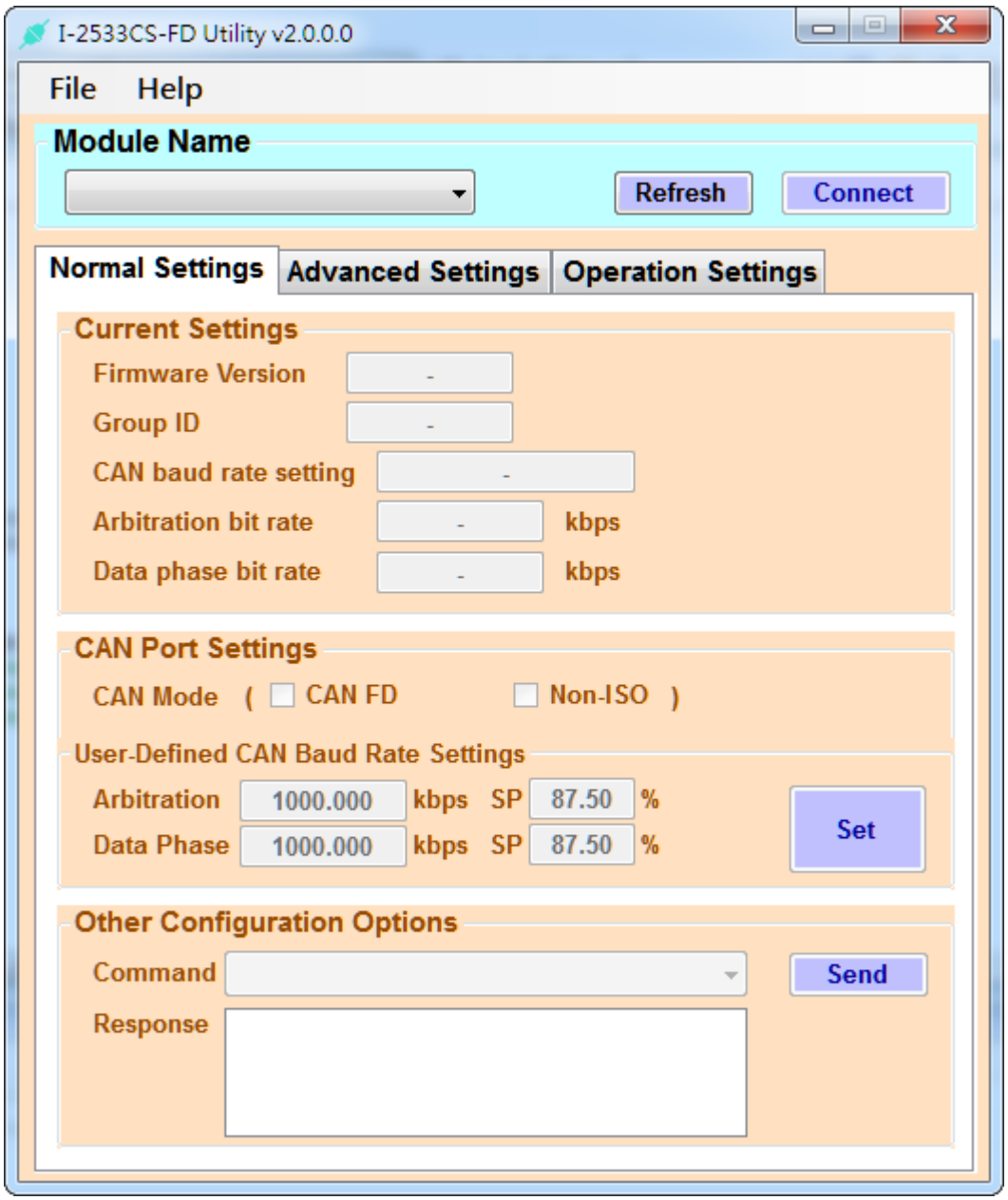

Figure 4-3-1 Main frame of the I-2533CS-FD Utility tool

[Normal Settings]
This field is used to get the current module settings, set user-defined CAN/CAN FD baud rate and configure other parameters.

[Advanced Settings]
This field is used to configure the CAN ID filter of the module.

[Operation Settings]
This field is used to configure the network parameters of the module.

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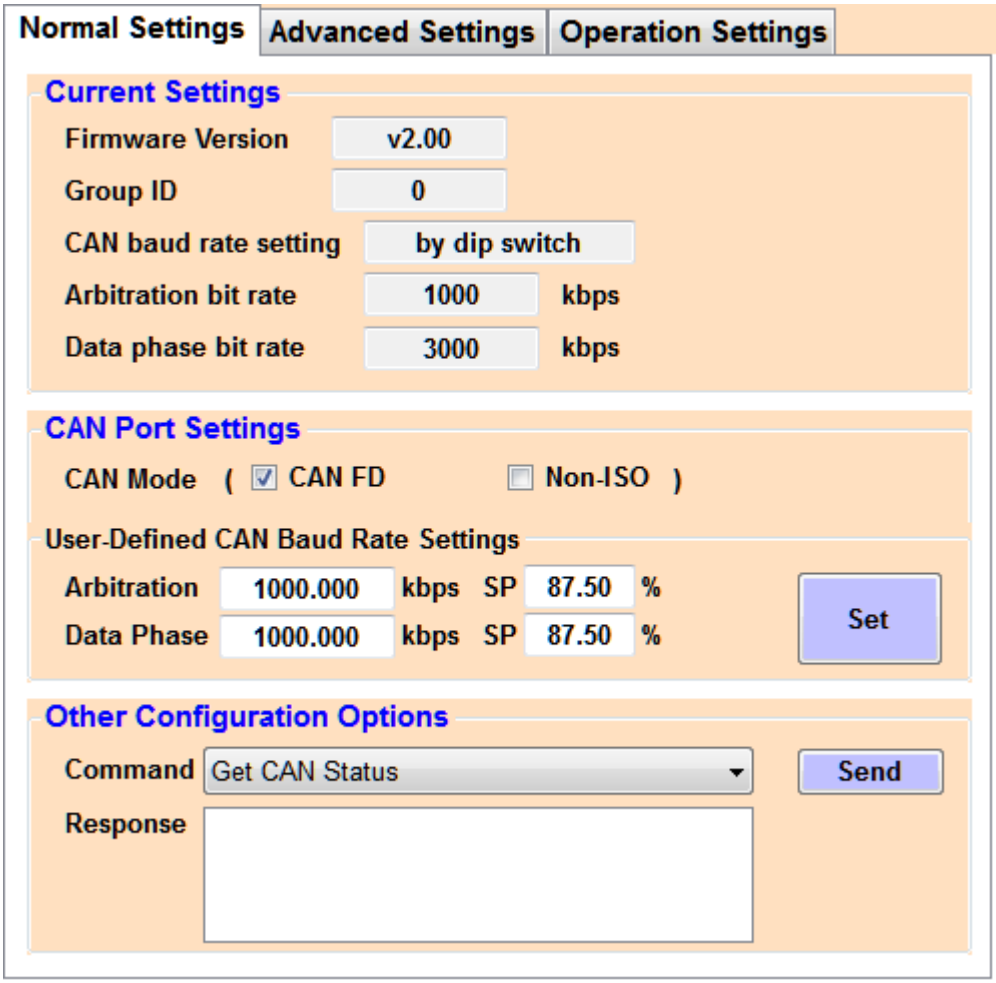
4.3.1. Connect to the module

Press the “Refresh” button to scan and list all the necessary I-2533CS-FD series modules on “Module Name” location.

Then select the necessary I-2533CS-FD series module and press “Connect” button to start to connect with it.



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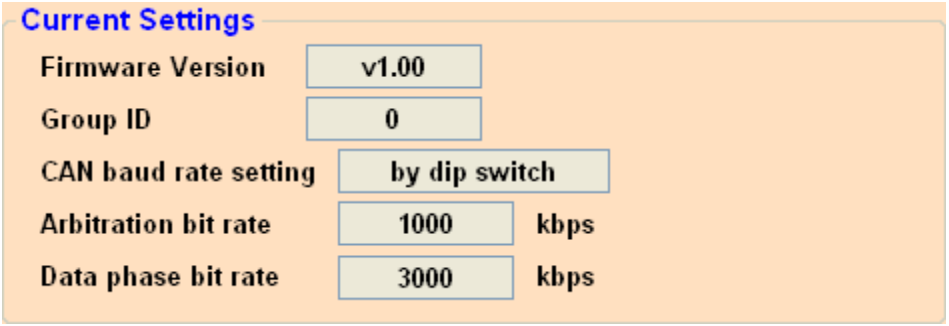
4.3.2. Get Current Module Settings

After successfully connect with the module, the current settings of module will be listed on “Current Settings” frame.



[Current Settings]

“Firmware Version”: Firmware version of the I-2533CS-FD series module.

“Group ID”: Group ID setting of the I-2533CS-FD series module.

“CAN baud rate setting”: Current CAN baud rate setting that the I-2533CS-FD series module used.

“Arbitration bit rate”: Current CAN/CAN FD arbitration phase bit rate the I-2533CS-FD series module used.

“Data phase bit rate”: Current CAN FD data phase bit rate the I-2533CS-FD series module used.

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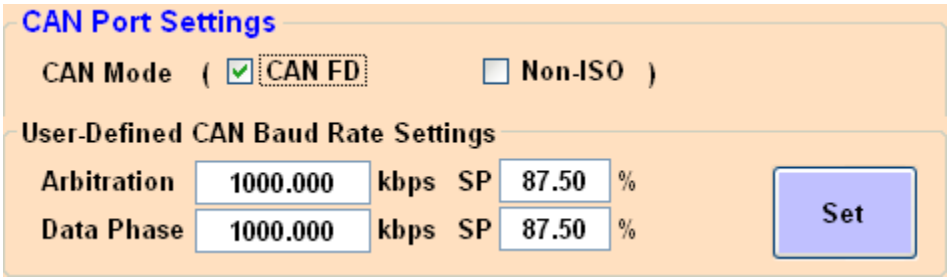
4.3.3. Configure User-Defined CAN Baud Rate

User also can set the CAN port operation mode and user-defined CAN baud rate parameter of the module. In order to use the “User-Defined CAN Baud Rate Settings” parameters, user needs to set the pin7 of “10-pin dip switch” to ON position. Otherwise, the “Arbitration Bit Rate” and “Data Phase Bit Rate” settings will follow according to “10-pin dip switch” settings.



Users can set parameters such as CAN port operation mode and CAN communication baud rate in the “CAN Port Settings” field. All settings will take effect after reboot the module. The detailed functions are as follows:

[CAN Mode]

“CAN FD”: Set the CAN port into CAN FD mode. When setting the CAN port into CAN FD mode, the CAN port can process CAN/CAN FD messages, otherwise this port just can process CAN messages.

“Non-ISO”: Non-ISO operation. If this parameter is checked, the module uses the CAN FD frame format as specified by the Bosch CAN FD Specification V1.0. Otherwise, CAN FD frame format will follow according to ISO11898-1.

[User-defined CAN Baud Rate Settings]

“Arbitration”: CAN/CAN FD arbitration phase bit rate. Valid range: 10 kbps ~ 1000 kbps.

“Data Phase”: CAN FD data phase bit rate. Valid range: 100 kbps ~ 10000 kbps

“SP”: CAN/CAN FD arbitration/data phase bit rate sample point. Suggested range: 75.00 ~ 87.50 %

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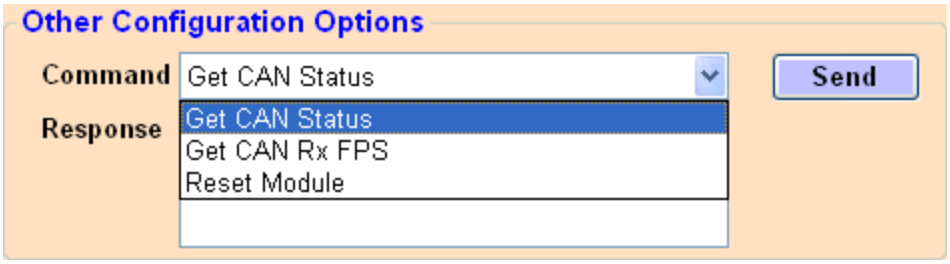
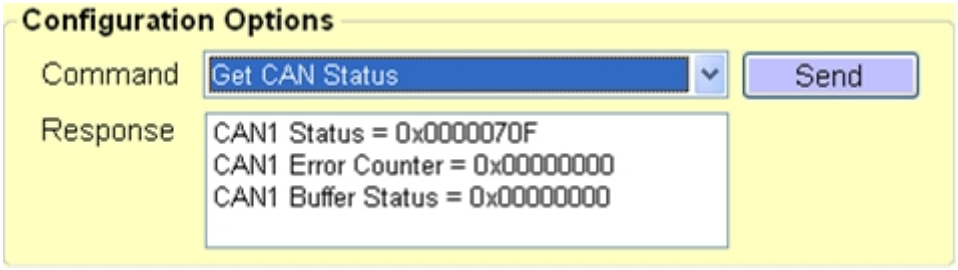
4.3.4. Configure Other Parameters

From the “Configuration Options” block, user can get the module CAN status (CAN Bus status, Error counter, and buffer status), CAN Rx FPS(received CAN message frame per second) and reset the module.



[Get CAN Status] command:



<1> “**CAN Status**” item:
0x: value in hexadecimal format.
Please refer to appendix 7.3 for “CAN Status” definition.

<2> “**CAN Error Counter**” item:
0x: value in hexadecimal format.
Please refer to appendix 7.4 for “CAN Error Counter” definition.

<3> “**CAN Buffer Status**” item:
0x: value in hexadecimal format.

Bit	Symbol	Value	Description
0	RX		CAN receive software buffer status
		0	Receive software buffer underrun
		1	Receive software buffer overrun
1	TX		CAN transmit software buffer status
		0	Transmit software buffer underrun
		1	Transmit software buffer overrun
3:2	-		Reserved
4	EW		CAN Error Warning status.
		0	Both error counters are below the Error Warning limit of 96
		1	At least one of error counter has reached the Error Warning limit of 96

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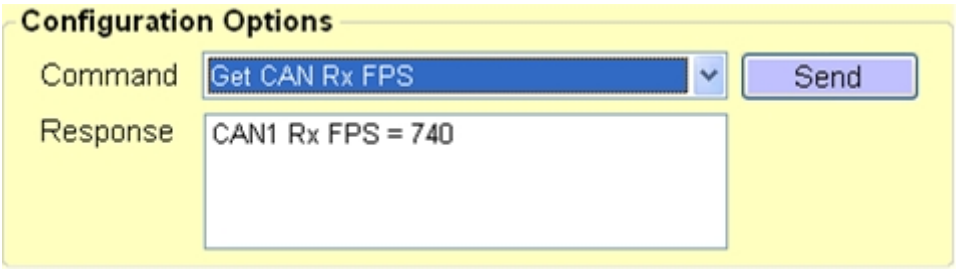
5	EP		CAN Error passive status
		0	The CAN is in Error Active state.
		1	The CAN is in the Error Passive state
6	BO		CAN Bus Off status
		0	The CAN is not in Bus OFF state.
		1	The CAN is in the Bus OFF state
31:7	-	-	Reserved

[Get CAN Rx FPS] command:



<1> "**CAN Rx FPS**" item:
CAN received CAN message frame per second.

[Reset Module] command:
Reset the module.

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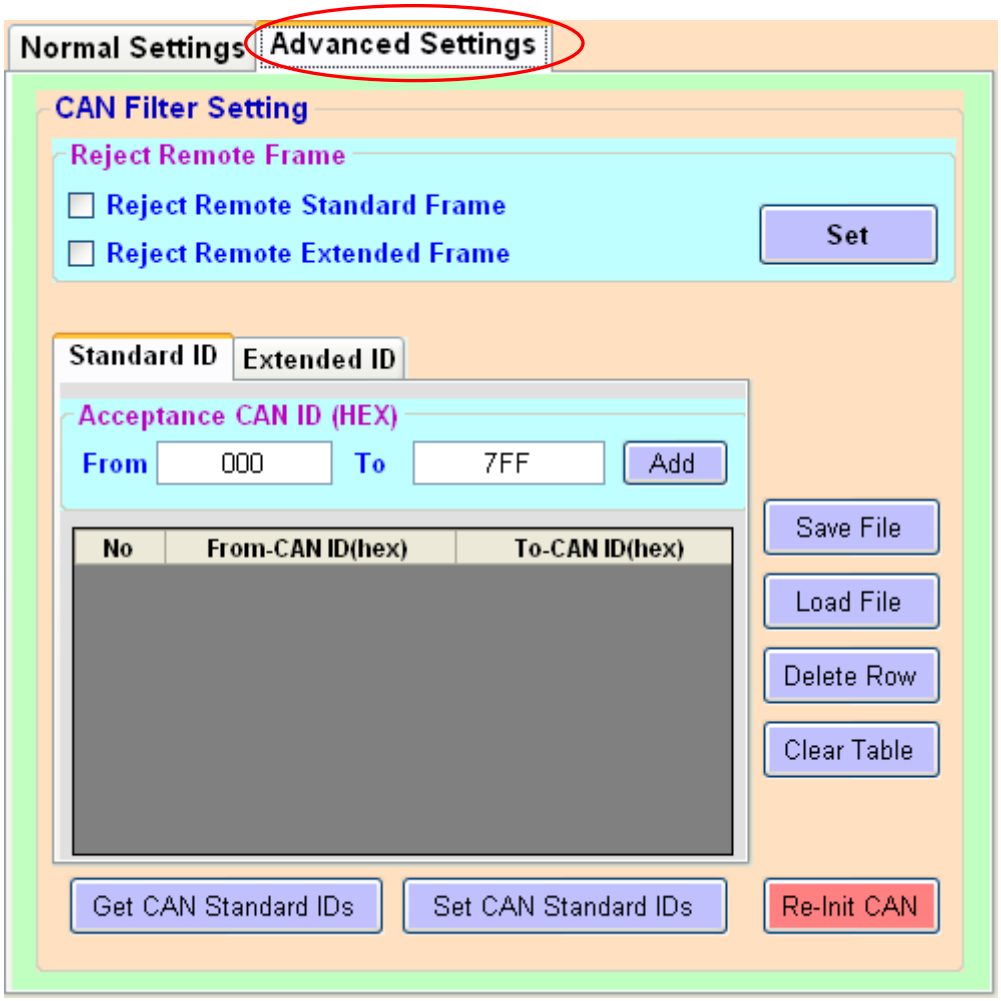
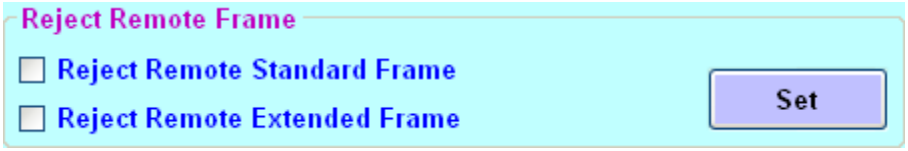
4.3.5. Configure CAN ID Filter

By using the I-2533CS-FD Utility tool, user can configure the CAN ID filter of the module.



The “Reject Remote Frame” is used to reject remote standard/extended CAN frame. And the “Standard ID/Extended ID” field are used to set accepted standard/extended CAN IDs. All settings in the “CAN Filter Setting” will take effect after pressing “Re-Init CAN” button.

[Reject Remote Frame] block:



<1> “**Set**” button:
Checking the “Reject Remote Standard/Extended Frame” item to select whether reject remote standard/extended CAN frame or not. After checking the “Reject Remote Frame”, press the “Set” button to save the setting into module.

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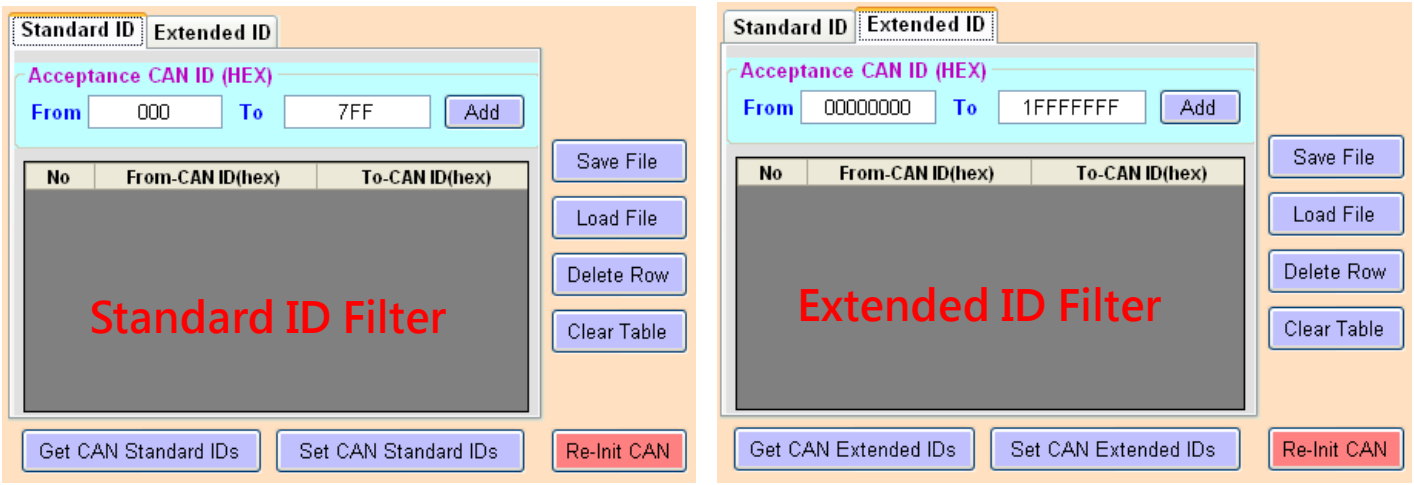
[Standard ID/Extended ID] block:



"**CAN ID (HEX)**" block:

Press the "Add" button to add a range of standard/extended CAN ID into "Standard/Extended ID Filter" frame.

<1> "**Get CAN Standard IDs/Get CAN Extended IDs**" button:
Get all the CAN Standard/Extended IDs setting from the module.

<2> "**Set CAN Standard IDs/Set CAN Extended IDs**" button:
Set the CAN Standard/Extended IDs setting on "Standard/Extended ID Filter" frame into the module.

<3> "**Re-Init CAN**" button:
All settings in the "CAN Filter Setting" will take effect after pressing "Re-Init CAN" button.

<4> "**Save File**" button:
Save the CAN Standard/Extended IDs setting on "Standard/Extended ID Filter" frame into an ini file.

<5> "**Load File**" button:
Load the CAN Standard/Extended IDs setting from a selected ini file to "Standard/Extended ID Filter" frame.

<6> "**Delete Row**" button:
Delete a selected row CAN ID from "Standard/Extended ID Filter" frame.

<7> "**Clear Table**" button:
Delete all CAN IDs from "Standard/Extended ID Filter" frame.

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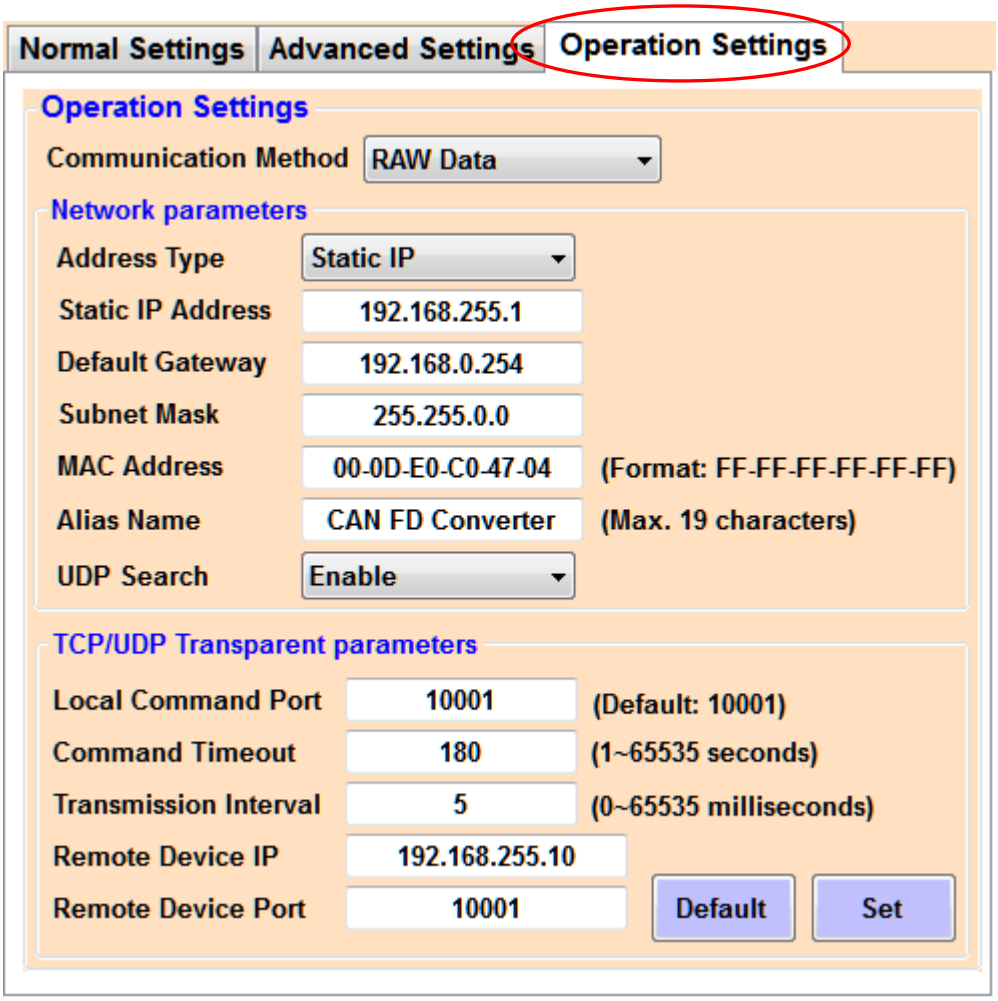
4.3.6. Configure Operation Settings

The module supports multiple communication methods via fiber, including **RAW Data**, **TCP**, and **UDP transparent modes**. Using the **I-2533CS-FD Utility tool**, users can easily configure the module's operation settings to suit their specific networking needs. (Firmware v2.00 support)



[Communication Method]
The module supports multiple communication methods, including **RAW Data**, **TCP**, and **UDP transparent modes**.

1. RAW Data Mode:
This is a general communication method that uses the IEEE 802.3 frame format (the standard Ethernet frame format) to transmit messages over optical fiber. However, unlike typical Ethernet communication where the data field follows well-known protocols (such as IPv4), the RAW data method uses specific protocols within the data field. It provides a raw, un-encapsulated data transmission method that allows for special communication needs and avoids the encapsulation and processing of higher-layer protocols.

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2. TCP Transparent Mode:

In **TCP Transparent** mode, the **I-2533CS-FD series module** acts as a **bridge** between **TCP client devices** (Max. support two clients) and the **CAN/CAN FD network** over a **fiber-optic** connection. This mode allows seamless communication between devices using TCP/IP and the CAN network, enabling the two different protocols to interact transparently.

- **TCP Client to CAN Network:**
  - TCP client devices, which typically communicate over fiber using TCP/IP, can send commands to the I-2533CS-FD series module.
  - These commands are transmitted in CAN/CAN FD format (as described in section 5 of the documentation).
  - The I-2533CS-FD module then converts the received TCP commands into CAN/CAN FD messages.
  - These messages are subsequently sent to the CAN network, allowing the TCP client to interact with devices connected to the CAN network.

- **CAN Network to TCP Client:**
  - Similarly, when the I-2533CS-FD series module receives CAN/CAN FD messages from the CAN network, it converts these messages into the appropriate commands (as described in section 5 of the documentation).
  - The converted commands are then sent back to the TCP client device via the fiber connection.
  - This allows the TCP client device to receive and process data from the CAN network in a transparent manner.

3. UDP Transparent Mode:

In **UDP Transparent** mode, the **I-2533CS-FD series module** acts as a **bridge** between **UDP devices** and the **CAN/CAN FD network** over a **fiber-optic** connection. This mode allows seamless communication between devices using UDP/IP and the CAN network, enabling the two different protocols to interact transparently.

- **UDP Devices to CAN Network**
  - UDP devices, which typically communicate over fiber using UDP/IP, can send commands to the I-2533CS-FD series module.
  - These commands are transmitted in CAN/CAN FD format (as described in section 5 of the documentation).
  - The I-2533CS-FD series module then converts the received UDP commands into CAN/CAN FD messages.
  - These messages are subsequently sent to the CAN network, allowing the UDP device to interact with devices connected to the CAN network.

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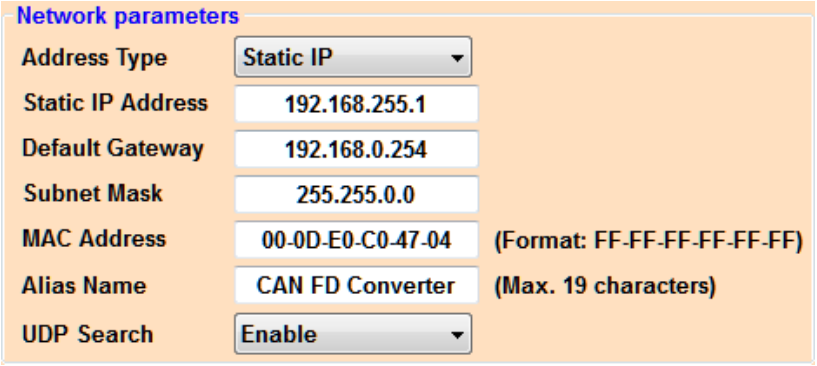
- **CAN Network to UDP Devices**
  - Similarly, when the I-2533CS-FD series module receives CAN/CAN FD messages from the CAN network, it converts these messages into the appropriate commands (as described in section 5 of the documentation).
  - The converted commands are then sent back to the UDP device via the fiber connection.
  - This allows the UDP device to receive and process data from the CAN network in a transparent manner.

[Network parameters]



The following is an overview of the parameters contained in the network parameters section. These parameters will take effect when the communication method is set to TCP or UDP transparent mode.

Item	Description
Address Type	**Static IP:** If no DHCP server is installed on the network, the network settings can be configured manually.
	DHCP: The Dynamic Host Configuration Protocol (DHCP) is a network application protocol that automatically assigns an IP address to each device.
Static IP Address	Each I-2533CS-FD series connected to the network must have its own unique IP address. This parameter is used to assign a specific IP address.
Subnet Mask	This parameter is used to assign the subnet mask for the I-2533CS-FD device. The subnet mask indicates which portion of the IP address is used to identify the local network or subnet.
Default Gateway	This parameter is used to assign the subnet mask for the I-2533CS-FD device. The subnet mask indicates which portion of the IP address is used to identify the local network or subnet.
MAC Address	This parameter is used to set the MAC address, which must be in the format FF-FF-FF-FF-FF-FF.
Alias Name	This parameter is used to assign an alias for each I-2533CS-FD series device to assist with easy identification.
UDP Search	This parameter is used to enable or disable UDP configuration function of eSearch tool.

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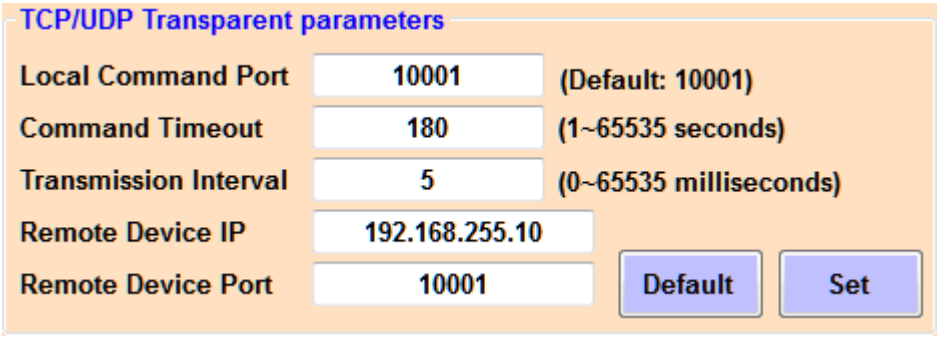
[TCP/UDP Transparent parameters]



The following is an overview of the parameters contained in the TCP/UDP Transparent parameters section. These parameters will take effect when the communication method is set to TCP or UDP transparent mode.

Item	Description	Default
Local Command Port	This parameter is used to configure the I-2533CS-FD series local command port to a custom value depending on your requirement.	10001
Command Timeout	If the local command port does not receive any data for a certain period, the I-2533CS-FD series can disconnect the socket. Settings range value: 1 ~ 65535 (seconds); Disabled: 0;	180
Transmission Interval	Interval for polling the CAN port and sending data to Fiber Settings range value: 0 ~ 65535 (millisecond)	5
Remote Device IP	The IP setting of the remote device. Used only in UDP Transparent Mode.	192.168. 255.10
Remote Device Port	The port setting of the remote device. Used only in UDP Transparent Mode.	10001
Set button	Click this button to save the revised settings to the I-2533CS-FD series device. All settings will take effect after rebooting the device.	
Default button	Click this button to restore all settings of the I-2533CS-FD series device. All settings will take effect after rebooting the device.	

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5. Fiber Command Information

When the communication method of the I-2533CS-FD series module is set to TCP/UDP Transparent Mode, TCP/UDP client devices can access the I-2533CS-FD module using the fiber commands in CAN/CAN FD format listed in this section. The I-2533CS-FD series module then converts these fiber commands into CAN/CAN FD format messages and sends them to the CAN network. Similarly, when CAN/CAN FD format messages are received from the CAN network, the I-2533CS-FD series converts the messages to fiber commands and sends them to the connected TCP/UDP client device.

5.1. Fiber/CAN FD Command

When the "Communication Method" setting is TCP or UDP Transparent mode, the Fiber command that I-2533CS-FD series supports for transmitting and receiving CAN FD messages are described in the table below and following sections.

Command Header Field			Command Data Field (Max. 18 Data)			
Header	**Type**	**Length**	**Data-1**	**Data-2**	**…**	**Data-N**
1 byte	1 byte	2 bytes	80 Bytes	80 Bytes	…	80 Bytes

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5.1.1. Command Header Field

The command header field contains three parameters, header, type and length.

Command Header Field		
Header	**Type**	**Length**
1 byte	1 byte	2 bytes

Parameters	Size (Byte)	Description
Header	1	The content of this parameter is fixed to the value of **0x55**.
Type	1	The content of the “Command Data Field” is used for CAN Port 1. **0x01:** The content of the “Command Data Field” is used for CAN Port 1. **Others: Reserved, for future used.**
Length	2	Total Length of the “Command Data Field” The “Length” parameter is meaning length of “Command Data Field”. The length of each data in “Command Data Field” is fixed at 80 Bytes. And a single command can be up to 18 data. So the content of Length must be 80 multiple N (N: 1~18, data number). For Example: ● One Data ➔ Length = 80 ● Two Data ➔ Length = 80 x 2 = 160 ● … ● Eighteen Data ➔ Length = 80 x 18 = 1440 **When the content of “Type” parameter is other values**: This parameter will be reserved and no used.

All the parameters are in 8-bit and 16-bit (1 and 2 bytes) format. The data for 16-bit (2 bytes) size is in high-byte first format. For example: 0x0A0B ➔ 0x0A, 0x0B

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5.1.2. Command Data Field

The command data field contains several data (maximum 18 data) which each data size is fixed to 80 bytes. The content of the data is listed in following table.

Command Data Field (Max. 18 Data)			
Data-1	**Data-2**	**…**	**Data-N**
80 Bytes	80 Bytes	…	80 Bytes

Data-N		
Parameters	**Size (Byte)**	**Description**
CAN Message ID	4	CAN ID of Standard or Extended CAN/CAN FD Frame. Standard Frame: use 11 bits CAN ID Extended Frame: use 29 bits CAN ID
CAN Message Format	2	Message Format. [bit15:6] : Reserved [bit5] : ESI[1], 0 – Active Error, 1 – Passive Error [bit4] : EVE, 0 – Normal message [bit3] : BRS[2], 0 – bit rate not switch, 1 – bit rate switch [bit2] : XTD, 0 – Standard frame, 1 – Extended frame [bit1] : RTR[3], 0 – Data frame, 1 – Remote frame [bit0] : FDF, 0 – CAN frame, 1 – CAN FD frame
CAN Data Length Code	2	Data Length Code[5] of the CAN/CAN FD frame length CAN Frame: 0 ~ 8 ➔ 0 ~ 8 data bytes CAN FD Frame: 0 ~ 8 ➔ 0 ~ 8 data bytes, 0x9 ~ 0xF ➔ 12, 16, 20, 24, 32, 48, 64 data bytes
CAN Data	64[4]	Content of CAN Data. CAN Frame ➔ maximum use 8 bytes data, no used for others CAN FD Frame ➔ maximum use 64 bytes data
Timestamp (sec)	4	Timestamp of received CAN message (unit: second). Reserved and no used for transmitted CAN message
Timestamp (micro-sec)	4	Timestamp of received CAN message (unit: micro second). Reserved and no used for transmitted CAN message

All the parameters are in 16-bit and 32-bit (2 and 4 bytes) format. The data for 16-bit (2 bytes) size is in high-byte first format. For example: 0x0A0B ➔ 0x0A, 0x0B. And the data for 32-bit (4 bytes) size is in high-byte first. For example: 0x0A0B0C0D ➔ 0x0A, 0x0B, 0x0C, 0x0D.

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NOTE:

[1]: This ESI bit is valid when receiving a CAN FD frame。

[2]: CAN FD frame bit rate switchable. This BRS bit is valid when FDF=1.

[3]: When FDF=1, the RTR bit cannot set to 1.

[4]: The size of CAN Data is fixed to 64 bytes. When the “CAN Message format” is a CAN frame, this field will use up to 8 bytes of data. When it is a CAN FD frame, this field will use up to 64 bytes of data.

[5]: Mapping table of Data Length Code to Frame data length

Data Length Code (Hexadecimal)	Frame data length (Decimal)	Data Length Code (Hexadecimal)	Frame data length (Decimal)
0x0	0	0x8	8
0x1	1	0x9	12
0x2	2	0xA	16
0x3	3	0xB	20
0x4	4	0xC	24
0x5	5	0xD	32
0x6	6	0xE	48
0x7	7	0xF	64

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5.1.3. Fiber Command Examples

◆ **Example 1:**

Transmit a CAN message from CAN1 of I-2533CS-FD which frame format is listed below

- Standard CAN frame which CAN ID is 0x123
- CAN Data length is 4 with data 0x11, 0x22, 0x33, 0x44

Transmitted Fiber command will like below table.

Command	Data Content (Hexadecimal)	Note
Command Header Field		
Header	0x55	
Type	0x01	CAN1
Data Length	0x00 0x50	80 bytes
Command Data Field - Data1		
CAN Message ID	0x00 0x00 0x01 0x23	
CAN Message Format	0x00 0x00	
CAN Data Length Code	0x00 0x04	4 bytes
CAN Data	0x11 0x22 0x33 0x44 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00	4 bytes data valid
Timestamp (sec)	0x00 0x00 0x00 0x00	Reserved
Timestamp (micro-sec)	0x00 0x00 0x00 0x00	Reserved

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◆ **Example 2:**

Transmit one CAN message and one CAN FD message from CAN1 of I-2533CS-FD by using one command which frame format is listed below

CAN message #1

- Extended CAN frame which CAN ID is 0x12345678
- CAN Data length is 2 with data 0x11, 0x22

CAN message #2

- Standard CAN FD frame which CAN ID is 0x123
- CAN Data length is 16 with data 0x01, 0x02, 0x03, 0x04, 0x05, 0x06, 0x07, 0x08, 0x09, 0x0A, 0x0B, 0x0C, 0x0D, 0x0E, 0x0F, 0x10
- Transmit this CAN FD message with bit rate switch enable

Transmitted Fiber command will like below table.

Command	Data Content (Hexadecimal)	Note
Command Header Field		
Header	0x55	
Type	0x01	CAN1
Data Length	0x00 0xA0	160 bytes
Command Data Field - Data1		
CAN Message ID	0x12 0x34 0x56 0x78	
CAN Message Format	0x00 0x04	
CAN Data Length Code	0x00 0x02	2 bytes
CAN Data	0x11 0x22 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00	2 bytes data valid
Timestamp (sec)	0x00 0x00 0x00 0x00	Reserved
Timestamp (micro-sec)	0x00 0x00 0x00 0x00	Reserved
Command Data Field - Data2		
CAN Message ID	0x00 0x00 0x01 0x23	
CAN Message Format	0x00 0x09	
CAN Data Length Code	0x00 0x0A	16 bytes

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CAN Data	0x01 0x02 0x03 0x04 0x05 0x06 0x07 0x08 0x09 0x0A 0x0B 0x0C 0x0D 0x0E 0x0F 0x10 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00	16 bytes data valid
Timestamp (sec)	0x00 0x00 0x00 0x00	Reserved
Timestamp (micro-sec)	0x00 0x00 0x00 0x00	Reserved

◆ **Example 3:**

Receive a CAN FD message from CAN1 of I-2533CS-FD at 10s.000us which frame format is listed below

- Extended CAN FD frame which CAN ID is 0x12345678
- CAN Data length is 8 with data 0x11, 0x22, 0x33, 0x44, 0x55, 0x66, 0x77 0x88
- CAN FD bit rate switch is enabled

Received Fiber command will like below table.

Command	Data Content (Hexadecimal)	Note
Command Header Field		
Header	0x55	
Type	0x01	CAN1
Data Length	0x00 0x50	80 bytes
Command Data Field - Data1		
CAN Message ID	0x12 0x34 0x56 0x78	
CAN Message Format	0x00 0x0D	
CAN Data Length Code	0x00 0x08	8 bytes
CAN Data	0x11 0x22 0x33 0x44 0x55 0x66 0x77 0x88 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00 0x00	8 bytes data valid
Timestamp (sec)	0x00 0x00 0x00 0x0A	10 s
Timestamp (micro-sec)	0x00 0x00 0x00 0x00	000 us

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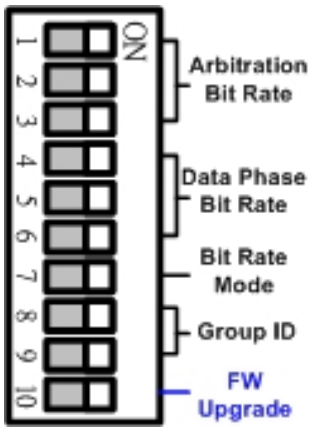
6. Firmware Upgrade

Please refer to the following steps to upgrade the firmware of I-2533CS-FD series module.

Step 1: Power off the I-2533CS-FD.

Step 2: Set the I-2533CS-FD's pin 10 of 10-pin dip switch to 'ON' position.

10-pin dip switch	Pin	Switch Function	Description
	10	Firmware upgrade mode	**ON:** Into firmware upgrade mode. **OFF:** Into normal operating mode.

Step 3: Power on the I-2533CS-FD, the CAN_Err, CAN_Tx, CAN_Rx, FB_Err LEDs will flash per 500 milliseconds.

Step 4: Connect the PC available USB port with the USB port of the I-2533CS-FD. Users can use a Mini-B type USB communication cable (CA-USB10) to connect with the module.

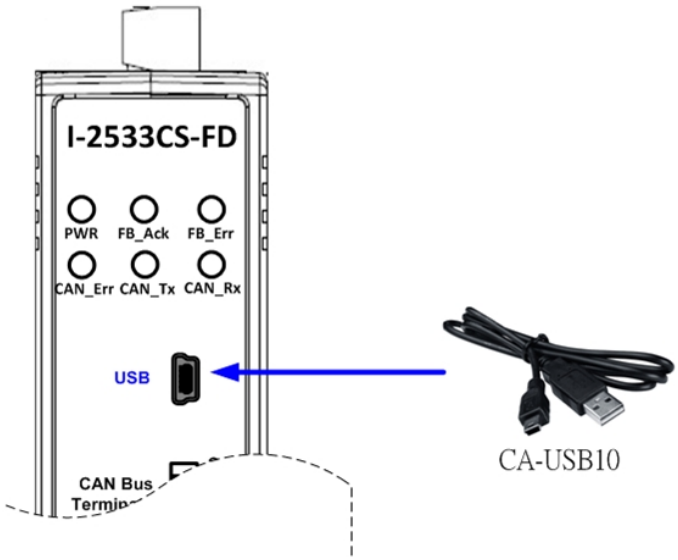


Figure 6-1 Wire connection of the USB

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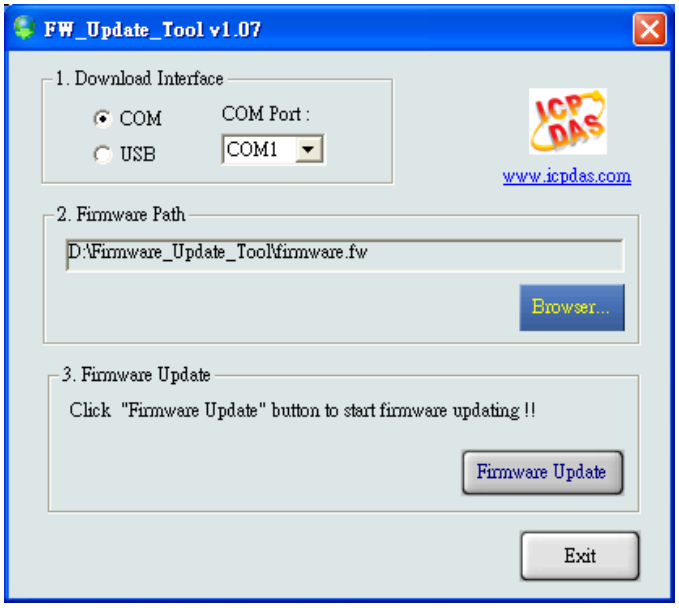
Step 5: At this time, the I-2533CS-FD module will be simulated as a “USB Mass Storage Device”, and one more “USB Disk” window, will pop up on the PC side. Then users can upgrade the firmware of the I-2533CS-FD module via this USB disk.

Step 6: Get the “Firmware Update Tool” and firmware fire.
The “Firmware Update Tool” is located at:
http://www.icpdas.com/en/download/show.php?num=2454&model=I-2533CS-FD

The firmware is located at:
http://www.icpdas.com/en/download/show.php?num=2455&model=I-2533CS-FD

Step 7: Execute the “Firmware Update Tool”.



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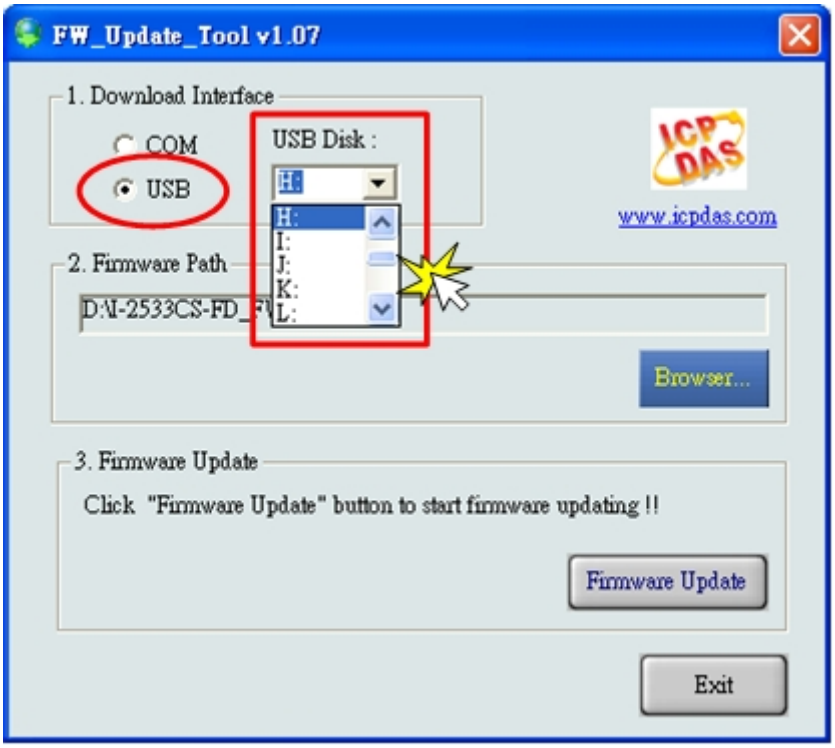
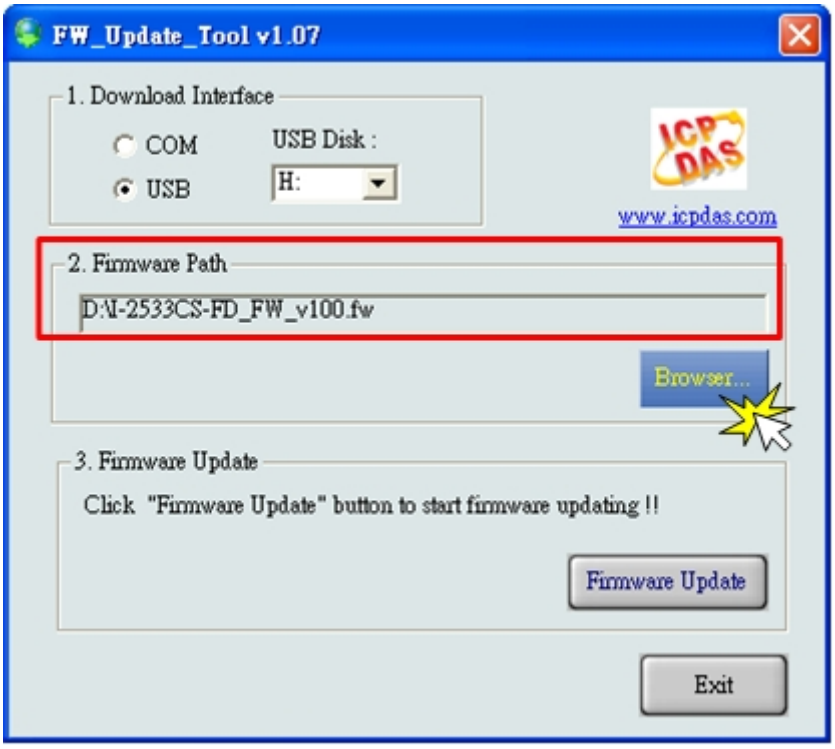
Step 8: Select USB port and the necessary USB Disk of PC



Step 9: Press the “Browser…” button and select the firmware file (*.fw).



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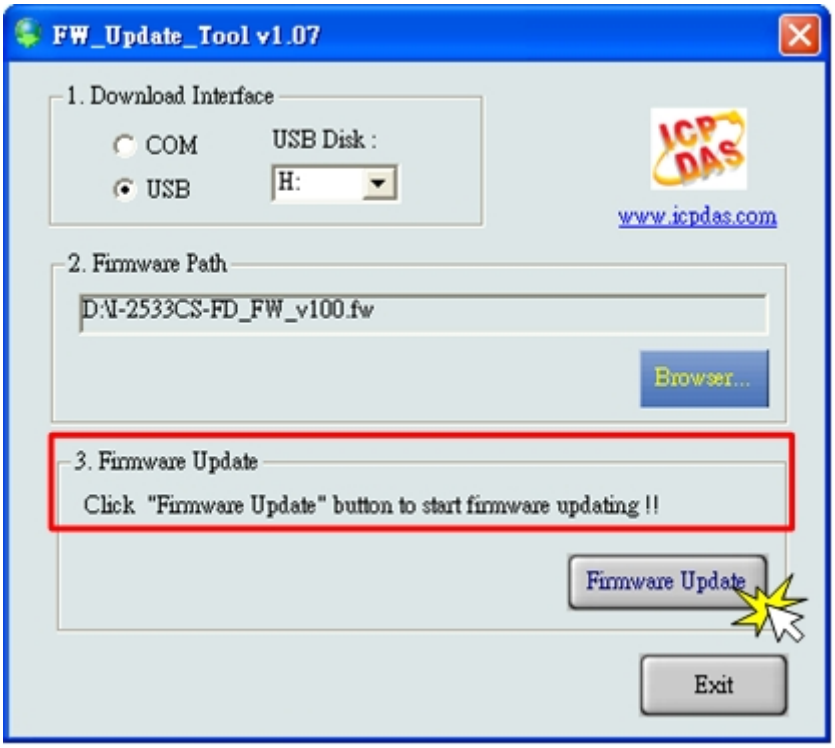
Step 10: Press the “Firmware Update” button to update the firmware. After successfully to update the firmware, the “Firmware Update Success! Please Reboot Module!” information will be display on the “3. Firmware Update” frame.



Step 11: Set the 10-pin dip switch to the necessary position and reboot the module. Then press the “Exit” button to exit.

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7. Appendix

7.1. Revision History

This chapter provides revision history information to this document.
The table below shows the revision history.

Revision	Date	Description
1.0.0	2020/06/01	Initial issue
1.1.0	2021/01/25	Upgrade CAN FD data bit rate to 10000 kbps
1.2.0	2021/04/12	Add appendix 6.5 for valid data phase bit rate that module support.
1.3.0	2023/01/16	Add appendix 6.6 for EMI Ferrite Split/Snap-On Core
2.0.0	2025/02/24	Add section 4.3.6 and section 5.
2.1.0	2026/04/09	Add I-2533CS-FD-A, I-2533CS-FD-B and I-2533CS-FD-60 modules

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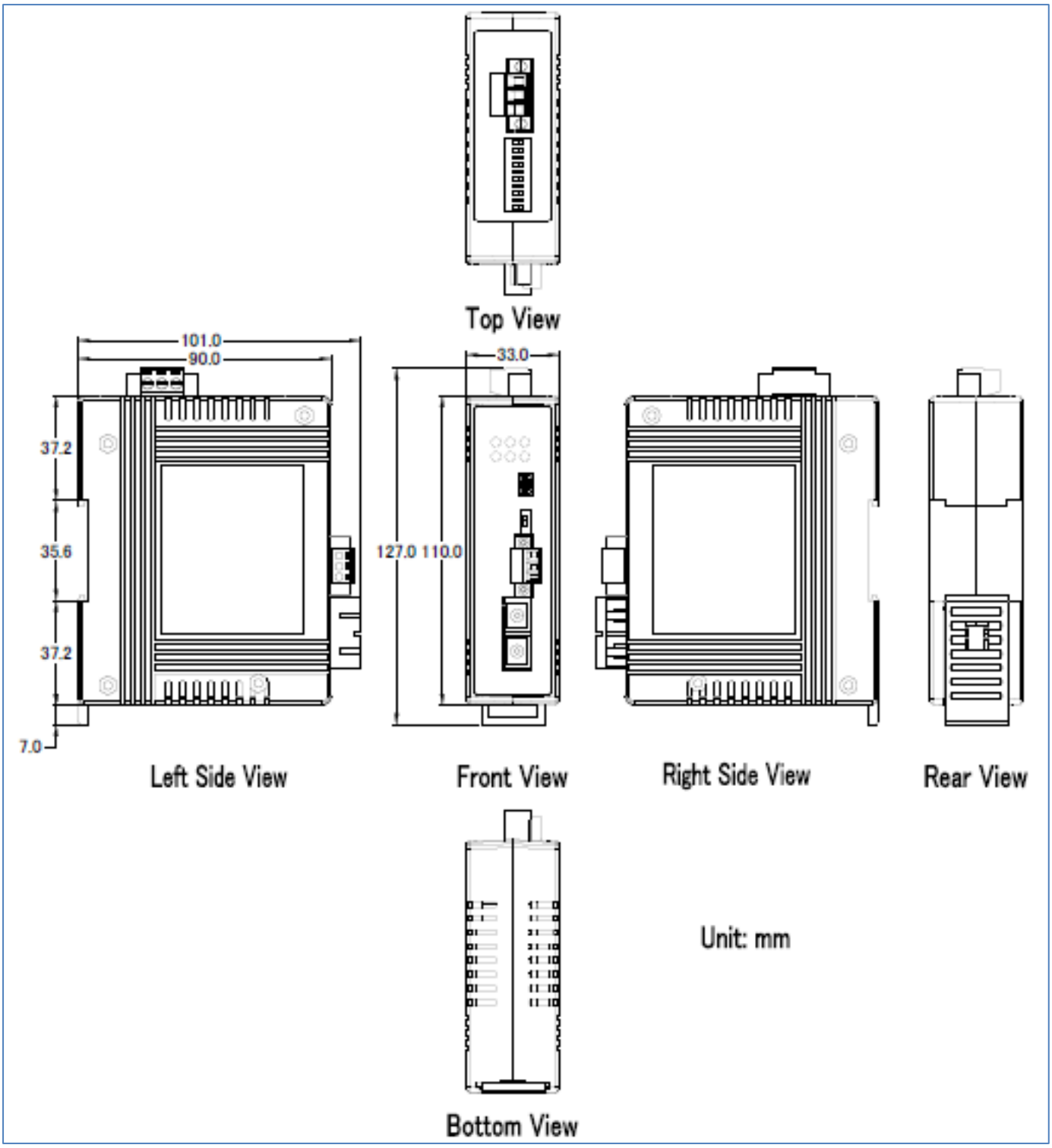
7.2. Dimension



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7.3. CAN Status Register

Bit	Symbol	Value	Description
2:0	LEC		**Last error code** These bits indicate the type of the last error to occur on the CAN bus. This bit field will be cleared when a message has been transferred without error. The bits in this bit field will be set upon a read access.
		0x0	**No error.**
		0x1	**Stuff error**: More than 5 equal bits in a sequence have occurred in a part of a received message where this is not allowed.
		0x2	**Form error**: A fixed format part of a received frame has the wrong format.
		0x3	**Ack Error**: The message transmitted by the M_CAN was not acknowledged by another node.
		0x4	**Bit1Error**: During the transmission of a message (with the exception of the arbitration field), the device wanted to send a recessive level (bit of logical value 1), but the monitored bus value was dominant.
		0x5	**Bit0Error**: During the transmission of a message (or acknowledge bit, or active error flag, or overload flag), the device wanted to send a dominant level (data or identifier bit logical value 0), but the monitored bus value was recessive. During Bus Off recovery this status is set each time a sequence of 11 recessive bits has been monitored. This enables the CPU to monitor the proceeding of the Bus Off recovery sequence (indicating the bus is not stuck at dominant or continuously disturbed).
		0x6	**CRC Error**: The CRC check sum of a received message was incorrect. The CRC of an incoming message does not match with the CRC calculated from the received data.
		0x7	**Unused**: No CAN Bus event was detected
4:3	ACT		Activity. This register monitors the CAN communication state.
		0x0	**Synchronizing** – node is synchronizing on CAN communication.
		0x1	**Idle** – node is neither receiver nor transmitter.
		0x2	**Receiver** – node is operating as receiver
		0x3	**Transmitter** – node is operating as transmitter.
5	EP		Error passive
		0	The CAN controller is in the error active state.
		1	The CAN controller is in the error passive state as defined in the CAN 2.0 specification.
6	EW		Warning status
		0	Both error counters are below the Error Warning limit of 96
		1	At least one of error counter has reached the Error Warning limit of 96
7	BOFF		Bus off status
		0	The CAN module is not in bus off state.
		1	The CAN controller is in bus off state.
31:8	-	-	Reserved

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7.4. CAN Error Counter Register

Bit	Symbol	Value	Description
7:0	TEC		Transmit error counter Current value of the transmit error counter (maximum value 255)
14:8	REC		Receive error counter Current value of the receive error counter (maximum value 127).
15	RP		Receive error passive
		0	Below error level. The receive counter is below the error passive level of 128
		1	At error level. The receive counter has reached the error passive level of 128
31:16	-	-	Reserved

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7.5. Valid Data Phase Bit Rat

	Supported Data Phase Bit Rate (kbps)				
Items	0	1	2	3	4
0	10000.000	8571.429	7500.000	6666.667	6000.000
5	5454.545	5000.000	4615.385	4285.714	4000.000
10	3750.000	3529.412	3333.333	3157.895	3000.000
15	2857.143	2727.273	2608.696	2500.000	2400.000
20	2307.692	2222.222	2142.857	2068.966	2000.000
25	1935.484	1875.000	1818.182	1764.706	1714.286
30	1666.667	1621.622	1578.947	1538.462	1500.000
35	1463.415	1428.571	1395.349	1363.636	1333.333
40	1304.348	1276.596	1250.000	1224.49	1200.000
45	1176.471	1153.846	1132.075	1111.111	1090.909
50	1071.429	1052.632	1034.483	1016.949	1000.000
55	983.6066	967.7419	952.381	937.500	923.0769
60	909.0909	895.5224	882.3529	869.5652	857.1429
65	845.0704	833.3333	821.9178	810.8108	800.000
70	789.4737	779.2208	769.2308	759.4937	750.000
75	740.7407	731.7073	722.8916	714.2857	705.8824
80	697.6744	689.6552	681.8182	674.1573	666.6667
85	659.3407	652.1739	645.1613	638.2979	631.5789
90	625.000	618.5567	612.2449	606.0606	600.000
95	594.0594	588.2353	582.5243	576.9231	571.4286
100	566.0377	560.7477	555.5556	550.4587	545.4545
105	540.5405	535.7143	530.9735	526.3158	521.7391
110	517.2414	512.8205	508.4746	504.2017	500.000
115	495.8678	491.8033	487.8049	483.871	480.000
120	476.1905	472.4409	468.750	465.1163	461.5385
125	458.0153	454.5455	451.1278	447.7612	444.4444
130	441.1765	437.9562	434.7826	431.6547	428.5714
135	425.5319	422.5352	419.5804	416.6667	413.7931
140	410.9589	408.1633	405.4054	402.6846	400.000
145	397.351	394.7368	392.1569	389.6104	387.0968
150	384.6154	382.1656	379.7468	377.3585	375.000
155	372.6708	370.3704	368.0982	365.8537	363.6364
160	361.4458	359.2814	357.1429	355.0296	352.9412
165	350.8772	348.8372	346.8208	344.8276	342.8571

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170	340.9091	338.9831	337.0787	335.1955	333.3333
175	331.4917	329.6703	327.8689	326.087	324.3243
180	322.5806	320.8556	319.1489	317.4603	315.7895
185	314.1361	312.500	310.8808	309.2784	307.6923
190	306.1224	304.5685	303.0303	301.5075	300.000
195	298.5075	297.0297	295.5665	294.1176	292.6829
200	291.2621	289.8551	288.4615	287.0813	285.7143
205	284.3602	283.0189	281.6901	280.3738	279.0698
210	277.7778	276.4977	275.2294	273.9726	272.7273
215	271.4932	270.2703	269.0583	267.8571	266.6667
220	265.4867	264.3172	263.1579	262.0087	260.8696
225	259.7403	258.6207	257.5107	256.4103	255.3191
230	254.2373	253.1646	252.1008	251.046	250.000
235	248.9627	247.9339	246.9136	245.9016	244.898
240	243.9024	242.915	241.9355	240.9639	240.000
245 ~ 290	…				
290	202.7027	202.0202	201.3423	200.6689	200.000
295 ~ 365	…				
365	161.7251	161.2903	160.8579	160.4278	160.000
370~390	…				
390	151.5152	151.1335	150.7538	150.3759	150.000
395~470	…				
470	126.0504	125.7862	125.523	125.261	125.000
475 ~ 490	…				
490	120.9677	120.7243	120.4819	120.2405	120.000
495 ~ 590	…				
590	100.6711	100.5025	100.3344	100.1669	100.000

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7.6. EMI Ferrite Split/Snap-On Core

EMI Ferrite Split/Snap-On Core

Features

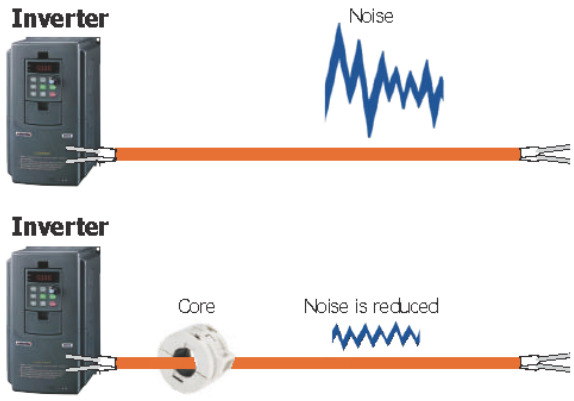
- Aimed to suppress low frequency noise generated by engine control units, inverters, and motors
- Split type
- Operation Temperature: -40 °C ~ 75 °C

Introduction

The split ferrite cable cores are designed to significantly reduce EMI/RFI for round cables.
The hinged plastic case surrounding the split core is designed to clamp onto the cable to provide a secure fixture of the ferrite onto the cable. The cores can be retrofitted onto existing installations or used in post-assembly operations on the data and power cables of electronic equipment. Ferrite cores are important for ensuring strong electronic signals through cables in environments where EMI or RFI can be an issue.

Applications

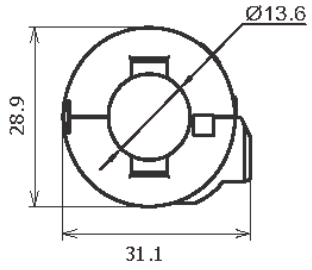
RS-232, RS-422, RS-485, CAN bus, FRnet, PROFIBUS, Ethernet, USB, AC/DC Power line..etc



Specifications

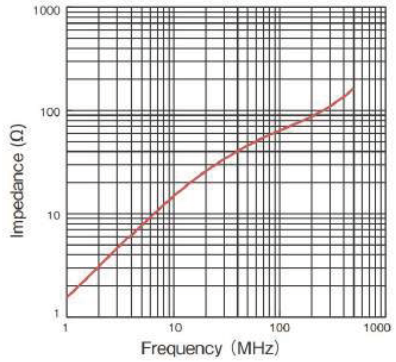
Max. Cable Diameter	Ø13 mm
Material Type	Board Band Material
Additional Description	Plastic Case
Case Color	White

Dimensions (Units: mm)



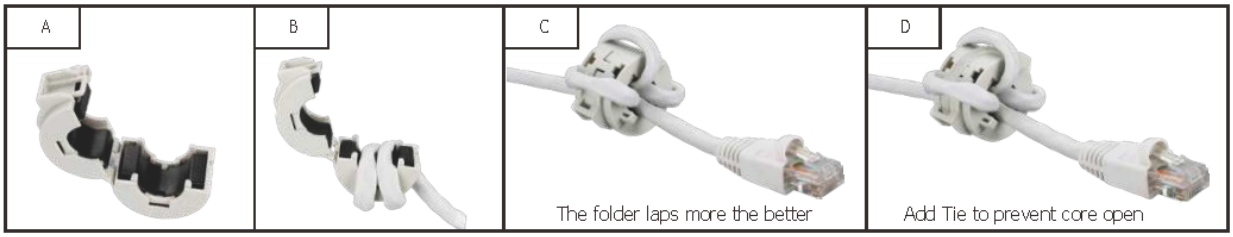
Front View | Left Side View

Characteristic



Test condition:
Wire: UEWφ0.5 mm / Length 50 mm / 1 Turn

Installation



Ordering Information

CD-002 CR	10 ferrite cores in one package (RoHS)

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