



User Manual

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ACS-20B(W)-MRTU

No-touch Infrared Sensor Switch



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Important Information

Warranty

All products manufactured by ICP DAS are under warranty regarding defective materials for a period of one year, beginning from the date of delivery to the original purchaser.

Warning

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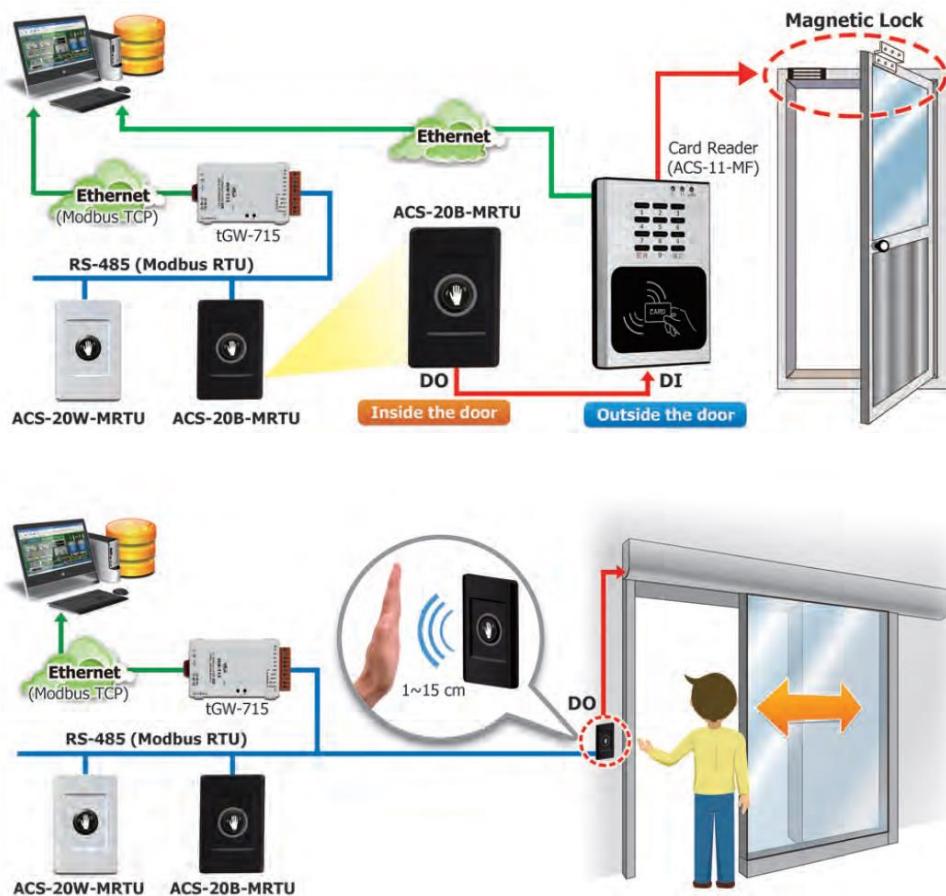
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Contact us

If you encounter any problems while operating this device, feel free to contact us via mail at: service@icpdas.com .

1. Introduction



▲ Figure 1-1 ACS-20B(W)-MRTU application architecture

The No-touch Infrared Sensor Switch from ICP DAS can be used to open a door using palm induction, which makes it more convenient when entering or exiting a room or building. The inductive distance and the delay time for door opening are adjustable, and has red and blue indicator lights to show the status of the switch. As people enter and exit the door using the No-touch Infrared Sensor Switches, a time stamp recording the action can be simultaneously logged.

The No-touch Infrared Sensor Switch includes an RS-485 interface and provides Modbus RTU communication, which can remotely enable/disable the switch and get the induction time records by the access control system.

Additionally, the No-touch Infrared Sensor Switch is not only used for the access control system but also helps you control other electronic devices. While it is triggered in toggle mode at the first time, the switch outputs ON signal, and next time outputs OFF signal.

The No-touch Infrared Sensor Switch can be used with electric doors to prevent issues related to the spread of infectious bacteria via touch. The switches can be used in medical institutions, retail stores, the food industry, industrial plants, and offices, etc. to provide an excellent sanitary environment.

1.1 Features

■ [ACS-20B-MRTU / ACS-20W-MRTU]

- ◆ Special infrared code to against interference
- ◆ Multiple operating modes: Sensing/Standby, Lock, Toggle Switch.
- ◆ Provides 8 locked periods each day
- ◆ Double-color status indicator
- ◆ Induction distance: 1 ~ 12 cm
- ◆ With Relay (N.C. and N.O. output)
- ◆ Relay hold time: 0.5 ~ 20 sec
- ◆ The switches time recording: 1,600 records
- ◆ Communication interface and protocol: RS-485/Modbus RTU

■ [Applications]

- ◆ Surveillance system
- ◆ Home and building automation
- ◆ Medical institutions
- ◆ Retail stores
- ◆ Food industry

2. Hardware

2.1 Specifications

▼ Table 2-1: Specification Table

| Model | ACS-20B-MRTU | ACS-20W-MRTU |
|----------------------|---|--------------|
| IR Interface | | |
| IR Output Ch. | 1 | |
| IR Input Ch. | 2 | |
| COM Ports | | |
| Ports | RS-485 (DATA+, DATA-) | |
| Baud Rate (bps) | 9600, 19200, 38400, 57600, 115200 | |
| Protocol | Modbus RTU (slave) | |
| LED Indicator | | |
| LED | Red (Standby); Blue (Sensing) [can be inverted] | |
| Relay Output | | |
| Channels | 1 | |
| Type | Form C | |
| Contact Rating | 2A@30VDC, 0.5A@120VAC, 0.25A@240VAC | |
| Power | | |
| Power Supply | +10 ~ +30 VDC | |
| Power Consumption | 0.9 W (Max.) | |
| Mechanical | | |
| Installation | Wall Mounting | |
| Dimensions | 75 mm x 119 mm x 24 mm (W x L x H) | |
| Cover Color | Black | White |
| Environment | | |
| Operating Temp. | -25 °C ~ +75 °C | |
| Storage Temp. | -30 °C ~ +80 °C | |
| Humidity | 10 ~ 90% RH, Non-condensing | |

2.2 Appearance



▲ Figure 2-1: ACS-20B-MRTU.



▲ Figure 2-2: ACS-20W-MRTU

2.3 Pin assignments

■ Terminals



▲ Figure 2-3: ACS-20B(W)-MRTU terminals

■ Cables

Table 2-2: Cables for ACS-20B(W)-MRTU terminal

| Cables | | | |
|---------|--------|---------------------------|-----------|
| Picture | Model. | Description | Interface |
| | CA-014 | +Vs (Red) (+10~+30VDC) | Power |
| | | GND (Black)- | |
| | CA-012 | NO (Blue) | Relay |
| | | COM (White) | |
| | | NC (Green) | |
| | CA-019 | DATA+ (Green) | RS-485 |
| | | DATA- (黃) | |

2.4 LED Indicators

There are circular red and blue led indicators on the ACS-20B/W-MRTU to show different operating states. The meanings of these states are described in Table 2-3.



▲ Figure 2-4: Red/Blue LED indicators of ACS-20B(W)-MRTU

▼ Table 2-3: Red/Blue LED indicators corresponding to module status

| LED | Circular LED Indicator | ACS-20B(W)-MRTU Status |
|-----|---|-------------------------------|
| Red | Red LED ON (NC & COM contacted) (*) | Standby; Toggle mode (ON) |
| | Blue LED ON (NO & COM contacted) (*) | IR sensing; Toggle mode (OFF) |
| | Red LED blinks once per 2 seconds | Locked mode |
| | Red & blue LED blink 2 times per second | Firmware update mode |

* The module status inverted if red and blue LEDs are inverted.

3. Configured by Hardware

3.1 Relay Hold Time

Relay hold time (off-delay time) after IR sensing can be set by the scale position “0~C” of the rotary switch (figure 3-1) as shown in table 3-1.



▲ Figure 3-1: Scale 0~C of rotary switch for relay hold time

▼ Table 3-1: relay hold time to the scale of the rotary switch

| scale | Relay hold time (sec) |
|-------|-----------------------|
| 0 | 0.5 |
| 1 | 1 |
| 2 | 2 |
| 3 | 3 |
| 4 | 4 |
| 5 | 5 |
| 6 | 6 |
| 7 | 7 |
| 8 | 8 |
| 9 | 9 |
| A | 10 |
| B | 15 |
| C | 20 |

3.2 Toggle Switch Mode

Rotate the rotary switch to the scale ‘D’ to be in the hardware Toggle Switch Mode. In this mode, sense the ACS-20B(W)-MRTU by hand once, the circular red LED is changed to blue (Relay: NO & COM contact). Then, sense the ACS-20B(W)-MRTU by hand once again, the blue LED will be changed back to red. (Relay: NC & COM contact)



▲ Figure 3-2: Scale 0~C of rotary switch for relay hold time

3.3 Sensing Range

Sensing range (sensed by palm of the hand) of ACS-20B(M)-MRTU can be adjusted by the rotary knob in figure 3-3. Rotate the knob clockwise to extend the sensing range (maximum 12 cm). Rotate the knob counterclockwise to reduce the sensing range (minimum 1 cm around). The scale is not linear between minimum and maximum limit. The default scale is rotated clockwise to the maximum limit.



▲ Figure 3-3: Rotary knob for sensing range (sensed by palm)

3.4 Restore Default Communication Settings

Rotate the rotary switch to the scale ‘E’. **Power cycle** the module to restore the default serial communication (Table).



▲ Figure 3-4: Rotate the rotary switch to ‘E’ scale for default communication.

▼ Table 3-2: relay hold time to the scale of the rotary s

| Item | Default value |
|-----------------------|---------------|
| Baud Rate | 9600 bps |
| Paritys | None |
| Data Bits | 8 |
| Stop Bits | 1 |
| Modbus Response Delay | 1 ms |
| Modbus Net ID | 1 |

4. Configured by Software

4.1 ACS-20 Utility

ACS-20 Utility is the configuration tool for ACS-20B(W)-MRTU. It runs in .NET Framework 4.5 based on Microsoft Windows OS. Users can download the ACS-20 Utility from:

ACS-20 Utility (ACS20_Util_Setup_v#i##i#.zip)

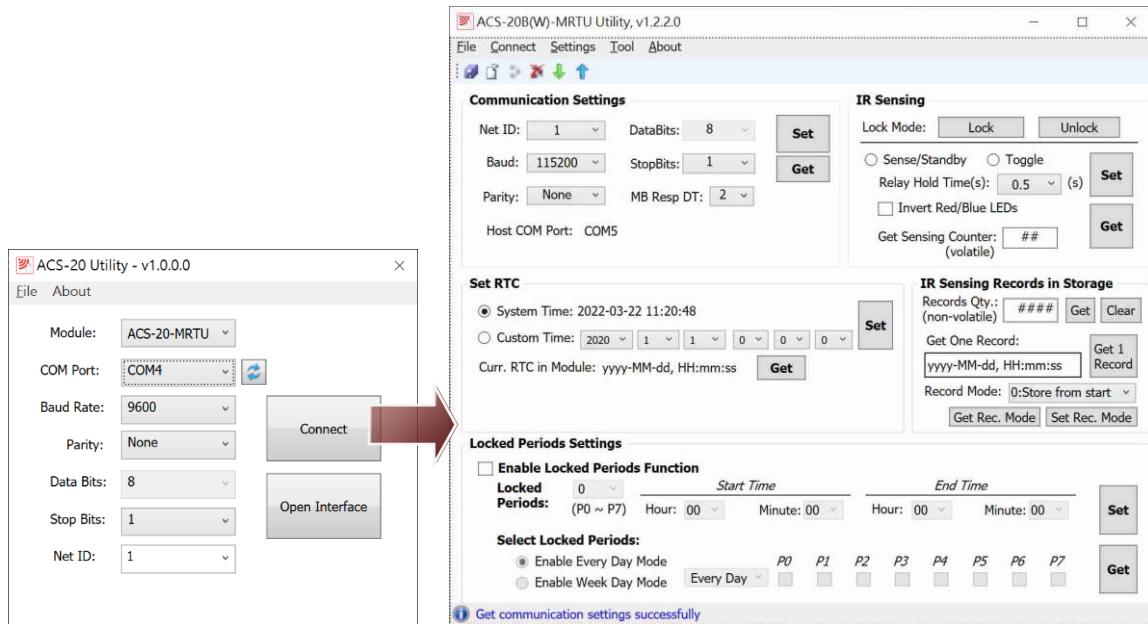
<https://www.icpdas.com/en/download/show.php?num=3154&model=ACS-20B-MRTU>

If the .NET Framework 4.5 is not available on the Microsoft OS, the setup package will download and install the redistribution automatically. The redistribution package can also be downloaded from the following link:

<https://www.microsoft.com/en-US/download/details.aspx?id=30653>

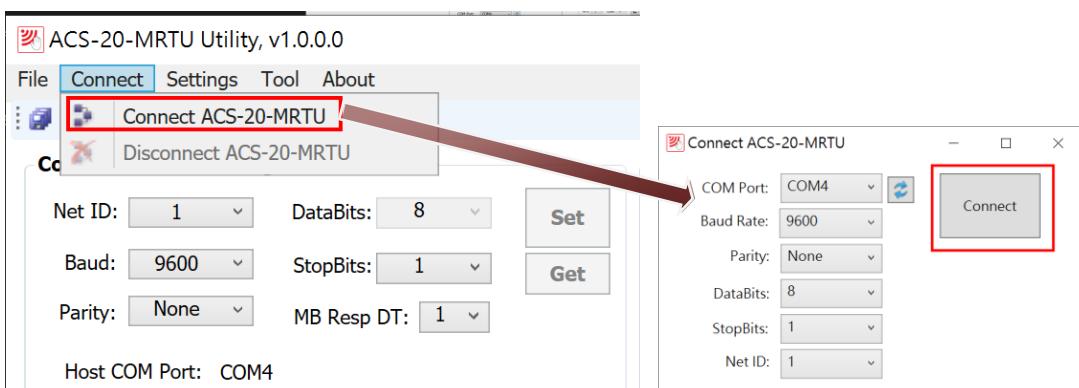
4.2 Serial Communication

The initial window of the ACS-20 utility is shown in the left of figure 4-1. Select the COM port of the host PC and the communication parameters of ACS-20B(W)-MRTU. Go to the main configuration window by clicking the “Connect” button.



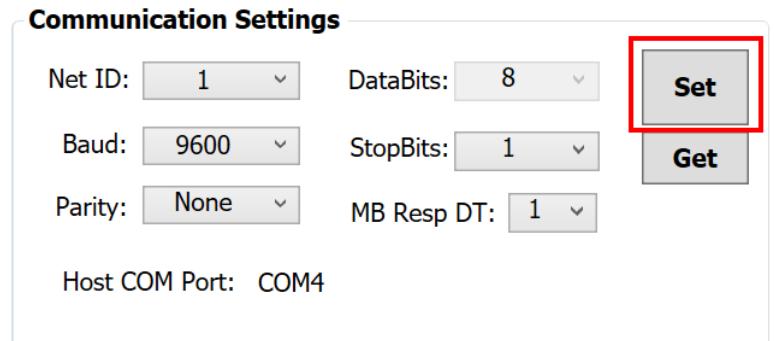
▲ Figure 4-1: Configuration window for ACS-20B(W)-MRTU.

If the main configuration window is opened by the “Open Interface” button, click menu [Connect] => [Connect ACS-20-MRTU] to open the connection window as shown in figure 4-2.



▲ Figure 4-2: Connection window for the main configuration window.

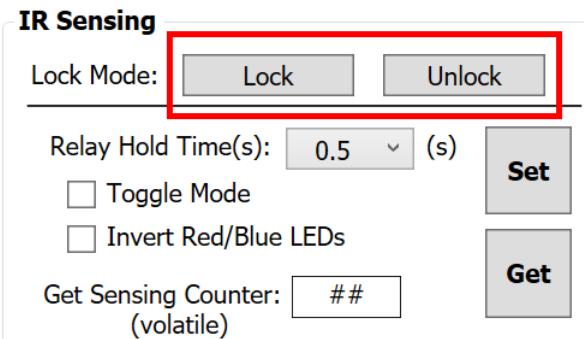
Set the communication parameters by clicking the “Set” button in the Communication Settings section in figure 4-3. Refer to chapter 5 for related Modbus command.



▲ Figure 4-3: Set communication settings.

4.3 Test Locked Mode

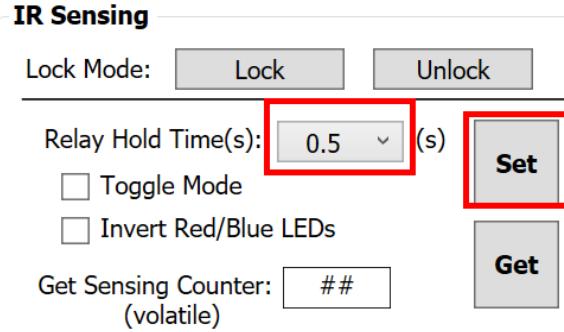
In the “IR Sensing” section of the utility, click “Lock” and “Unlock” button (figure 4-4) to test the locked mode. IR sensing function is disabled in this mode. Refer to chapter 5 for related Modbus command.



▲ Figure 4-4: Test locked mode.

4.4 Set Relay Hold Time

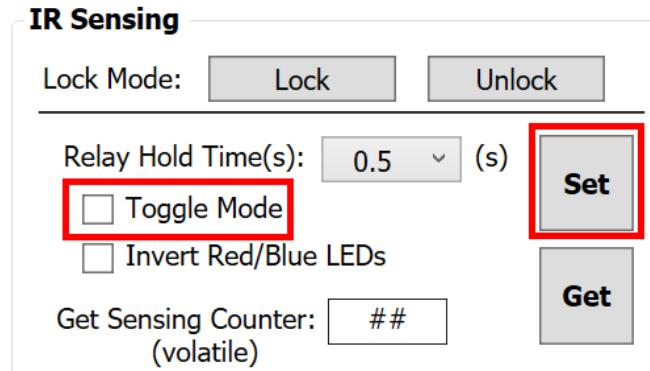
In the “IR Sensing” section of the utility, there are “0.5 ~ 20 sec” items in the “Relay Hold Time” combobox (figure 4-5) for selection. Click the “Set” button to set the parameter. Refer to chapter 5 for related Modbus register and command.



▲ Figure 4-5: Set relay hold time.

4.5 Set Toggle Mode

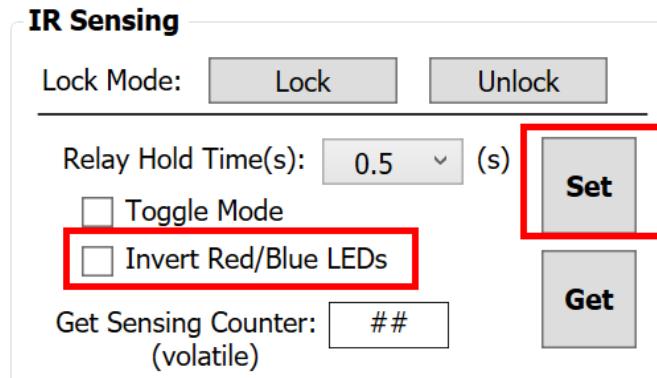
In the “IR Sensing” section of the utility, click the “Set” button after checking or unchecking the “Toggle Mode” checkbox as shown in figure 4-6. Refer to chapter 5 for related Modbus register and command.



▲ Figure 4-6: Set toggle mode.

4.6 Invert Red/Blue LED

In the “IR Sensing” section of the utility, click the “Set” button after checking or unchecking the “Invert Red/Blue LED” checkbox as shown in figure 4-7. Refer to chapter 5 for related Modbus register and command.

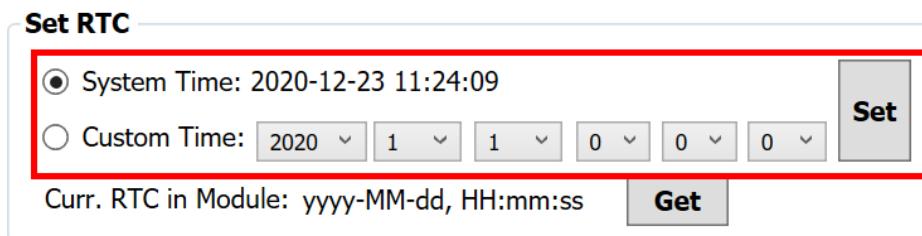


▲ Figure 4-7: Set inversion of Red/Blue LED.

4.7 Set RTC

There is built-in RTC (Real Time Clock) in ACS-20B(W)-MRTU. One RTC Time (Year/Month/Day, Hour:Minute:Second) is recorded when IR sensing by palm of hand.

In the “Set RTC” section (figure 4-8) of the utility, the time following the “System Time” radio button is the host system time. Customize the time by clicking the “Custom Time” radio button. Click the “Set” button to set RTC with the time following the selected radio button. Refer to chapter 5 for the related Modbus command to access RTC.



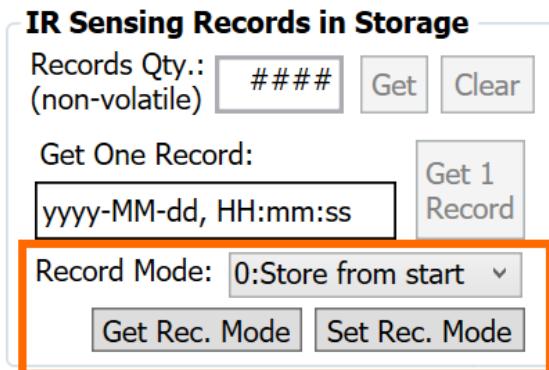
▲ Figure 4-8: Set RTC

4.8 Set IR Sensing Record Mode

The “Record Mode” in the “IR Sensing Records in Storage” section (figure 4-9) is for setting the storage mode when the storage is full. There are two modes:

Mode 0 (Store from start): (default) Clear all records and store from start.

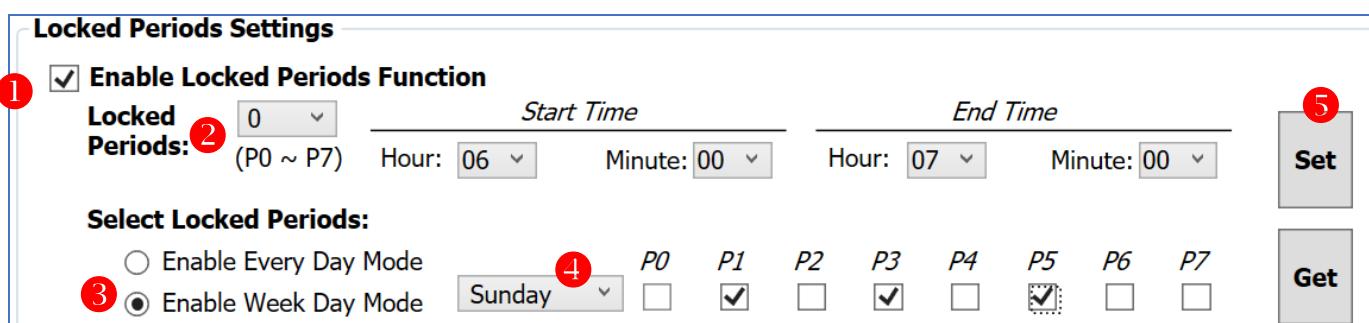
Mode 1 (Discard the latest): Discard new data and keep 1600 records of old data.



▲ Figure 4-9: Set IR sensing record mode.

4.9 Set Locked Periods

Locked periods can be set in the “Locked Periods Settings” section of the utility as shown in figure 4-10. The module goes into locked mode (no IR sensing) in the locked period.



▲ Figure 4-10: Set locked periods.

- (1) Check/Uncheck “Enabled Locked Periods Function” checkbox to enable/disable this

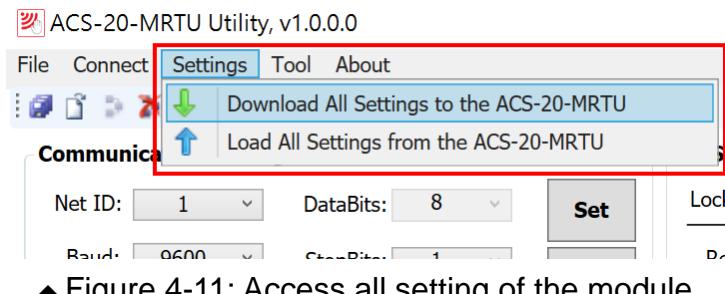
function.

- (2) Click the “Locked Periods” combobox to select 8 periods (0 ~ 7) for setting. The “End Time” should be more than the “Start Time”.
- (3) Click “Enable Every Day Mode” or “Enable Week Day Mode” radio button for “Every Day Mode” or “Week Day Mode” .
- (4) This combobox can set the locked periods for every day and weekdays (Sunday to Saturday) by checking or unchecking the P0 ~ P7 checkboxes to enable or disable them.
- (5) Click the right “Set” button to finish the setting.

4.10 Access All Settings

Separate settings can be set as previous sections. Or click Menu [Settings]=>[Download All Settings to the ACS-20-MRTU] to set all settings to the module at once after all parameters are selected in the utility.

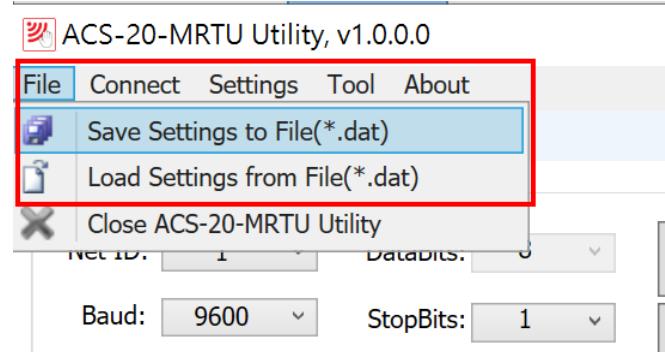
Click Menu [Settings]=>[Load All Settings from the ACS-20-MRTU] to read back all settings to utility from the module at once.



4.11 Configuration File

All settings in the utility can be saved to a configuration file by clicking Menu [File]>[Save Settings to File(*.dat)] where the file extension is dat.

Load all setting from a configuration file by clicking Menu [File]>[Load Settings from File(*.dat)]



▲ Figure 4-12: Access configuration file.

5. Modbus Command

The following Function Code commands are provided for a Modbus master to configure ACS-20B(W)-MRTU. Function Code 100 are manufacturer assigned commands for parameter settings to the module.

▼ Table 5-1: Modbus Function Code for ACS-20B(W)-MRTU

| Function Code | Description | Section |
|---------------|---------------------------------------|-----------------------|
| 4 (0x04) | Read multiple input registers (3xxxx) | 5.1.1 |
| 3 (0x03) | Read holding registers (4xxxx) | 5.1.2 |
| 6 (0x06) | Write single register (4xxxx) | 5.1.2 |
| 16 (0x10) | Write multiple registers (4xxxx) | 5.1.2 |
| 1 (0x01) | Read multiple coils status (0xxxx) | 5.1.3 |
| 5 (0x05) | Write single coil (0xxxx) | 5.1.3 |
| 15 (0x0F) | Force multiple coils (0xxxx) | 5.1.3 |
| 2 (0x02) | Read Discrete Inputs (1xxxx) | 5.1.4 |
| 100 (0x64) | Manufacturer defined function call. | 5.2 |

5.1 Modbus Register Table

This section provides Modbus registers for configuration. FC4 can be used to read status in section 5.1.1. FC1, FC5, FC15, FC3, FC6 and FC16 can be used to access the settings (provided for firmware version v1.6.0 and later). The same setting function can be done by the FC100 commands in section 5.2, too.

5.1.1 Modbus Input Registers

The Modbus Input Registers are listed in Table 5-2. They are read-only registers.

▼ Table 5-2: Modbus Input Registers (3xxxx)

| Address (1-based) | Address (0-based) | Description | R/W |
|----------------------|----------------------|--|-----|
| 30261 | 260 (0x0104) | Sensing Year (2000~2200) (The last IR sensing RTC time after power-on) | R |
| 30262 | 261 (0x0105) | Sensing Month (1~12) (The last IR sensing RTC time after power-on) | R |
| 30263 | 262 (0x0106) | Sensing Day (1~31) (The last IR sensing RTC time after power-on) | R |
| 30264 | 263 (0x0107) | Sensing Hour (0~23) (The last IR sensing RTC time after power-on) | R |
| 30265 | 264 (0x0108) | Sensing Minute (0~59) (The last IR sensing RTC time after power-on) | R |
| 30266 | 265 (0x0109) | Sensing Second (0~59) (The last IR sensing RTC time after power-on) | R |
| 30267 | 266 (0x010A) | Sensing Day of Week (0~6: Sun.~Sat.) (The last IR sensing RTC time after power-on) | R |
| 30268 | 267 (0x010B) | Quantity of stored IR sensing records (0~1600) | R |
| 30269 | 268 (0x010C) | IR Sensing status (0: not sensing, 1: sensing / toggle mode(always 1)) | R |
| 30270 | 269 (0x010D) | Value of rotary switch (0x00~0x0F) | R |
| 30271 | 270 (0x010E) | Current RTC Year (2000~2200) | R |
| 30272 | 271 (0x010F) | Current RTC Month (1~12) | R |
| 30273 | 272 (0x0110) | Current RTC Day (1~31) | R |
| 30274 | 273 (0x0111) | Current RTC Hour (0~23) | R |
| 30275 | 274 (0x0112) | Current RTC Minute (0~59) | R |
| 30276 | 275 (0x0113) | Current RTC Second (0~59) | R |
| 30277 | 276 (0x0114) | Current RTC Day of Week (0~6: Sunday~Saturday) | R |

5.1.2 Modbus Holding Registers

The Modbus Holding Registers are listed in Table 5-3. The access is read and write. Write values to the holding registers can change settings immediately, and some of them can be stored (non-volatile) in the module and some are not (volatile) after power cycling the module.

▼ Table 5-3: Modbus Holding Registers (4xxxx)

| Address (1-based) | Address (0-based) | Description | R/W |
|----------------------|----------------------|--|------|
| 40253 | 252 (0x00FC) | (reboot effected) Modbus Unit ID of Module : 1 ~ 247 , default = 1 | R,W |
| 40254 | 253 (0x00FD) | (reboot effected) Baud rate index : 6 ~ 10, default = 6 (6~10 => 9600, 19200, 38400, 57600, 115200 bps) | R,W |
| 40255 | 254 (0x00FE) | (reboot effected) Parity : 0=>None[default], 1=>Odd, 2=>Even | R,W |
| 40256 | 255 (0x00FF) | Databits: 8 (reserved, always 8) | R |
| 40257 | 256 (0x0100) | (reboot effected) Stopbits : 1[default], 2 | R,W |
| 40258 | 257 (0x0101) | (reboot effected) Modbus response delay (ms) : 0 ~ 30 ms (default = 3 ms) | R,W |
| 40260 | 259 (0x0103) | (volatile) Lock/unlock switch (0=>unlock, 1=>lock) (volatile) | R,W |
| 40261 | 260 (0x0104) | (volatile) Toggle mode (0=>disable, 1=>enable) (volatile) | R,W |
| 40266 | 265 (0x0109) | (volatile) (High word) Total number of IR sensing from power on. | R,W |
| 40267 | 266 (0x010A) | (volatile) (Low word) Total number of IR sensing from power on. | R,W |
| 40268 | 267 (0x010B) | Relay hold time (off-delay) (ms). value=500~20000 | R,W |
| 40269 | 268 (0x010C) | (volatile) Low byte : 1=> Clear all IR sensing records; 0=>Register value is 0 right after cleared all. (volatile) High byte : IR sensing recording. 0=>enable; 1=> disable | R, W |
| 40270 | 269 (0x010D) | Invert the Red/Blue LED for IR sensing. 0=>[default] Red (standby, NC contacts COM) / Blue (IR sensing, NO contacts COM) 1=>Red (IR sensing, NC contacts COM) / Blue (standby, NO contacts COM). | R,W |
| 40271 | 270 (0x010D) | Record mode of IR sensing RTC data when the storage is full. 0=>[default] overwrite the first record, 1=>neglect the new records, 2=>keep the latest records | R,W |
| 40274 | 273 (0x0111) | Set RTC Year : 2000 ~ 2200. Back to zero after setting. | W |
| 40275 | 274 (0x0112) | Set RTC Month : 1 ~ 12. Back to zero after setting. | W |

| | | | |
|-------|-----------------|--|-----|
| 40276 | 275 (0x0113) | Set RTC Day : 1 ~ 31. Back to zero after setting. | W |
| 40277 | 276 (0x0114) | Set RTC Hour : 0 ~ 23. Back to zero after setting. | W |
| 40278 | 277 (0x0115) | Set RTC Minute : 0 ~ 59. Back to zero after setting. | W |
| 40279 | 278 (0x0116) | Set RTC Second : 0 ~ 59. Back to zero after setting. | W |
| 40282 | 281 (0x0119) | Lock Period 0 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40283 | 282 (0x011A) | Lock Period 0 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40284 | 283 (0x011B) | Lock Period 1 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40285 | 284 (0x011C) | Lock Period 1 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40286 | 285 (0x011D) | Lock Period 2 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40287 | 286 (0x011E) | Lock Period 2 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40288 | 287 (0x011F) | Lock Period 3 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40289 | 288 (0x0120) | Lock Period 3 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40290 | 289 (0x0121) | Lock Period 4 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40291 | 290 (0x0122) | Lock Period 4 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40292 | 291 (0x0123) | Lock Period 5 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40293 | 292 (0x0124) | Lock Period 5 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40294 | 293 (0x0125) | Lock Period 6 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40295 | 294 (0x0126) | Lock Period 6 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40296 | 295 (0x0127) | Lock Period 7 Start : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40297 | 296 (0x0128) | Lock Period 7 End : Hour(0~23), Minute(0~59) [Start < End] | R,W |
| 40309 | 308 (0x0134) | 0x0080 => reboot module after 3 seconds | R |

5.1.3 Modbus Coils

The Modbus Coils are listed in Table 5-4. The access is read and write. Write values to the coils can change settings immediately and kept after power cycling the module.

Table 5-4: Modbus Coils (0xxxx)

| Address (1-based) | Address (0-based) | 描述 | R/W |
|----------------------|------------------------------|---|-----|
| 00017 | 16 (0x0010) | Enable/Disable locked period function ◦ 0=>disable; 1=>enable | R,W |
| 00019 | 18 (0x0012) | Day mode of locked period function 0=>everyday(default) ; 1=>weekday | R,W |
| 00028 ~ 00035 | 27 ~ 34 (0x001B~0x0022) | Enable/Disable locked period 0 ~ 7 (everyday mode) 0=>disable; 1=>enable | R,W |
| 00044 ~ 00051 | 43 ~ 50 (0x002B~0x0032) | Enable/Disable locked period 0 ~ 7 (Sunday) 0=>disable; 1=>enable | R,W |
| 00060 ~ 00067 | 59 ~ 66 (0x003B~0x0042) | Enable/Disable locked period 0 ~ 7 (Monday) 0=>disable; 1=>enable | R,W |
| 00076 ~ 00083 | 75 ~ 82 (0x004B~0x0052) | Enable/Disable locked period 0 ~ 7 (Tuesday) 0=>disable; 1=>enable | R,W |
| 00092 ~ 00099 | 91 ~ 98 (0x005B~0x0062) | Enable/Disable locked period 0 ~ 7 (Wednesday) 0=>disable; 1=>enable | R,W |
| 00108 ~ 00115 | 107 ~ 114 (0x006B~0x0072) | Enable/Disable locked period 0 ~ 7 (Thursday) 0=>disable; 1=>enable | R,W |
| 00124 ~ 00131 | 123 ~ 130 (0x007B~0x0082) | Enable/Disable locked period 0 ~ 7 (Friday) 0=>disable; 1=>enable | R,W |
| 00140 ~ 00147 | 139 ~ 146 (0x008B~0x0092) | Enable/Disable locked period 0 ~ 7 (Saturday) 0=>disable; 1=>enable | R,W |

5.1.4 Modbus Discrete Inputs

The Modbus Discrete Inputs are listed in Table 5-5. The R/W access is read-only. The Modbus Discrete Inputs are provided in the firmware version **1.6.5** and later.

Table 5-5: Modbus Coils (0xxxx)

| Address (1-based) | Address (0-based) | 描述 | R/W |
|----------------------|----------------------|--|-----|
| 10001 | 0 (0x0000) | Contact status of the relay. 0 => NC and COM are connected; 1 => NO and COM are connected. | R |

5.2 Modbus FC100 Commands

This section describes all sub function calls (sub-FC) of FC100 (0x64) for the settings on ACS-20B(W)-MRTU. All sub-FCs are listed in table 5-5. All setting values are non-volatile (effective after power-cycling the module). In the following sections, Modbus requests and responses are listed without CRC16 bytes.

▼ Table 5-6: Sub-FCs of FC100

| Sub-FC | Command Description | Section |
|------------|--|------------------------|
| 00 (0x00) | Get the module name. | 5.2.1 |
| 04 (0x04) | Set the Modbus unit ID (Net ID) of the module. | 5.2.2 |
| 05 (0x05) | Read communication settings. | 5.2.3 |
| 06 (0x06) | Set communication settings. | 5.2.4 |
| 07 (0x07) | Read current communication settings. | 5.2.5 |
| 08 (0x08) | Read Modbus response delay. | 5.2.6 |
| 09 (0x09) | Set Modbus response delay. | 5.2.7 |
| 32 (0x20) | Read firmware version. | 5.2.8 |
| 33 (0x21) | Read firmware date. | 5.2.9 |
| 34 (0x22) | Get stored quantity of IR sensing records. | 5.2.10 |
| 35 (0x23) | Clear all stored IR sensing records. | 5.2.11 |
| 39 (0x27) | Get RTC time. | 5.2.12 |
| 40 (0x28) | Set RTC time. | 5.2.13 |
| 41 (0x29) | Get IR sensing records data | 5.2.14 |
| 42 (0x2A) | Get IR sensing record mode. | 5.2.15 |
| 43 (0x2B) | Set IR sensing record mode. | 5.2.16 |
| 44 (0x2C) | Get inverted red/blue LED status. | 5.2.17 |
| 45 (0x2D) | Set inverted red/blue LED status. | 5.2.18 |
| 46 (0x2E) | Get relay hold time. | 5.2.19 |
| 47 (0x2F) | Set relay hold time. | 5.2.20 |
| 64 (0x40) | Get locked mode. | 5.2.21 |
| 65 (0x41) | Set locked mode. | 5.2.22 |
| 66 (0x42) | Get day mode of locked periods. | 5.2.23 |
| 67 (0x43) | Set day mode of locked periods. | 5.2.24 |
| 68 (0x44) | Get enabled state of locked periods. | 5.2.25 |
| 69 (0x45) | Set enabled state of locked periods. | 5.2.26 |
| 70 (0x46) | Get 8 locked periods. | 5.2.27 |
| 71 (0x47) | Set 8 locked periods. | 5.2.28 |
| 72 (0x48) | Get enabled state of locked period function. | 5.2.29 |
| 73 (0x49) | Set enabled state of locked period function. | 5.2.30 |
| 76 (0x4C) | Get scale value of rotary switch. | 5.2.31 |
| 77 (0x4D) | Get toggle mode | 5.2.32 |
| 78 (0x4E) | Set toggle mode | 5.2.33 |
| 165 (0xA5) | Reboot module | 5.2.34 |

5.2.1 Sub-FC00 (0x00): Get the Module Name

The request/response for getting the module name is listed in table 5-6 and table 5-7.

▼ Table 5-7: FC100-Sub-FC00 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x00 |

▼ Table 5-8: FC100-Sub-FC00 Response

| Byte order | Description | Size | Value |
|------------|-------------|----------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x00 |
| 03~14 | Module name | 12 Bytes | Hex ASCII code of characters. 0x00 is none. “ACS20MRTU”=> 0x41,0x43,0x53,0x32,0x30,0x4D,0x52,0x54,0x55, 0x00,0x00,0x00 |

5.2.2 Sub-FC04 (0x04): Set the Modbus Unit ID (Net ID)

▼ Table 5-9: FC100-Sub-FC04 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x04 |
| 03 | New Address | 1 Byte | 1 ~ 247 (Net ID) |
| 04 | [reserved] | 1 Byte | 0x00 |

▼ Table 5-10: FC100-Sub-FC04 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|--------------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x04 |
| 03 | Result | 1 Byte | 0x00 => OK, Others => Error |
| 04 | [reserved] | 1 Byte | 0x00 |

Note: This parameter setting is effective after power cycling the module,

5.2.3 Sub-FC05 (0x05): Get Communication Settings

▼ Table 5-11: FC100-Sub-FC05 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x05 |
| 03 | reserved | 1 Byte | 0x00 |

▼ Table 5-12: FC100-Sub-FC05 Response

| Byte order | Description | Size | Value |
|------------|-----------------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x05 |
| 03 | Net ID | 1 Byte | 1 ~ 247 (Net ID) of the module |
| 04 | Baud rate | 1 Byte | 6 ~ 10 (baud rate index) => {9600, 19200, 38400, 57600, 115200} bps |
| 05 | Parity | 1 Byte | 0, 1, 2=>{None, Odd, Even} (default: None) |
| 06 | Data bits | 1 Byte | 8 (fixed) |
| 07 | Stop bits | 1 Byte | 1, 2 (default: 1) |
| 08 | Modbus response delay | 1 Byte | 0 ~ 30 ms (default: 1 ms) |
| 09 | Reserved | 1 Byte | 0x00 |

5.2.4 Sub-FC06 (0x06): Set Communication Settings

▼ Table 5-13: FC100-Sub-FC06 Request

| Byte order | Description | Size | Value |
|------------|-----------------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x05 |
| 03 | New NetID | 1 Byte | 1 ~ 247 (Net ID) of the module |
| 04 | Baud rate | 1 Byte | 6 ~ 10 (baud rate index) => {9600, 19200, 38400, 57600, 115200} bps |
| 05 | Parity | 1 Byte | 0, 1, 2=>{None, Odd, Even} (default: None) |
| 06 | Reserved | 1 Byte | 0x00 |
| 07 | Stop bits | 1 Byte | 1, 2 (default: 1) |
| 08 | Modbus response delay | 1 Byte | 0 ~ 30 ms (default: 1 ms) |
| 09 | Change Setting | 1 Byte | 0=>The settings are effective after power cycling. 1=>Change settings immediately |

▼ Table 5-14: FC100-Sub-FC06 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|----------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x05 |
| 03 | Result | 1 Byte | 0=>OK 0xFF=>Error |

5.2.5 Sub-FC07 (0x07): Read Current Communication Settings

The settings read from Sub-FC05 is the settings by Sub-FC06 if the Byte 09 [Change Setting] of Sub-FC06 is 0 (The settings are effective after power-cycling). Sub-FC07 reads the settings before power-cycling the module.

▼ Table 5-15: FC100-Sub-FC07 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x07 |
| 03 | reserved | 1 Byte | 0x00 |

▼ Table 5-16: FC100-Sub-FC07 Response

| Byte order | Description | Size | Value |
|------------|-----------------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x07 |
| 03 | Net ID | 1 Byte | 1 ~ 247 (Net ID) of the module |
| 04 | Baud rate | 1 Byte | 6 ~ 10 (baud rate index) => {9600, 19200, 38400, 57600, 115200} bps |
| 05 | Parity | 1 Byte | 0, 1, 2=>{None, Odd, Even} (default: None) |
| 06 | Data bits | 1 Byte | 8 (fixed) |
| 07 | Stop bits | 1 Byte | 1, 2 (default: 1) |
| 08 | Modbus response delay | 1 Byte | 0 ~ 30 ms (default: 1 ms) |
| 09 | Reserved | 1 Byte | 0x00 |

5.2.6 Sub-FC08 (0x08): Get Modbus Response Delay

▼ Table 5-17: FC100-Sub-FC08 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x08 |

▼ Table 5-18: FC100-Sub-FC08 Response

| Byte order | Description | Size | Value |
|------------|-----------------------|--------|--------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x08 |
| 03 | Modbus Response Delay | 1 Byte | 0 ~ 30 ms (default: 1ms) |

5.2.7 Sub-FC09 (0x09): Set Modbus Response Delay

▼ Table 5-19: FC100-Sub-FC09 Request

| Byte order | Description | Size | Value |
|------------|-----------------------|--------|--------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x09 |
| 03 | Modbus Response Delay | 1 Byte | 0 ~ 30 ms (default: 1ms) |

▼ Table 5-20: FC100-Sub-FC09 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|----------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x09 |
| 03 | Result | 1 Byte | 0=>OK 0xFF=>Error |

5.2.8 Sub-FC32 (0x20): Get Firmware Version

▼ Table 5-21: FC100-Sub-FC32 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x20 |

▼ Table 5-22: FC100-Sub-FC32 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|----------------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x20 |
| 03 | Major | 1 Byte | Major number of firmware version |
| 04 | Minor | 1 Byte | Minor number of firmware version |
| 05 | Build | 1 Byte | Build number of firmware version |

5.2.9 Sub-FC33 (0x21): Get Firmware Date

▼ Table 5-23: FC100-Sub-FC33 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x21 |

▼ Table 5-24: FC100-Sub-FC33 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x21 |
| 03 | Year_MSB | 1 Byte | High byte of AD year, e.g. 0x07 of 0x07E5 (2021) |
| 04 | Year_LSB | 1 Byte | Low byte of AD year, e.g. 0xE5 of 0x07E5 (2021) |
| 05 | Month | 1 Byte | 1 ~ 12 |
| 06 | Day | 1 Byte | 1 ~ 31 |

5.2.10 Sub-FC34 (0x22): Get Stored Quantity of IR Sensing Records

▼ Table 5-25: FC100-Sub-FC34 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x22 |

▼ Table 5-26: FC100-Sub-FC34 Response

| Byte order | Description | Size | Value |
|------------|--------------|--------|------------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x22 |
| 03 | Quantity_MSB | 1 Byte | High byte of record quantity |
| 04 | Quantity_LSB | 1 Byte | Low byte of record quantity |

5.2.11 Sub-FC35 (0x23): Clear All Stored IR Sensing Records

▼ Table 5-27: FC100-Sub-FC35 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x23 |
| 03 | Reserved | 1 Byte | 0x00 |

▼ Table 5-28: FC100-Sub-FC35 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|--------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x23 |
| 03 | Result | 1 Byte | 0=>OK, 1=>Error |

5.2.12 Sub-FC39 (0x27): Get RTC Time

▼ Table 5-29: FC100-Sub-FC39 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x27 |

▼ Table 5-30: FC100-Sub-FC39 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x27 |
| 03 | Year_MSB | 1 Byte | High byte of AD Year, e.g. 07h of 07E5h (2021) |
| 04 | Year_LSB | 1 Byte | Low byte of AD Year, e.g. 0xE5 of 0x07E5 (2021) |
| 05 | Month | 1 Byte | 1 ~ 12 |
| 06 | Day | 1 Byte | 1 ~ 31 |
| 07 | Hour | 1 Byte | 0 ~ 23 |
| 08 | Minute | 1 Byte | 0 ~ 59 |
| 09 | Second | 1 Byte | 0 ~ 59 |
| 10 | Reserved | 1 Byte | 0x00 |

5.2.13 Sub-FC40(0x28): Set RTC Time

▼ Table 5-31: FC100-Sub-FC40 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x28 |
| 03 | Year_MSB | 1 Byte | High byte of AD Year, e.g. 07h of 07E5h (2021) |
| 04 | Year_LSB | 1 Byte | Low byte of AD Year, e.g. 0xE5 of 0x07E5 (2021) |
| 05 | Month | 1 Byte | 1 ~ 12 |
| 06 | Day | 1 Byte | 1 ~ 31 |
| 07 | Hour | 1 Byte | 0 ~ 23 |
| 08 | Minute | 1 Byte | 0 ~ 59 |
| 09 | Second | 1 Byte | 0 ~ 59 |
| 10 | Reserved | 1 Byte | 0x00 |

▼ Table 5-32: FC100-Sub-FC40 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|----------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x28 |
| 03 | Result | 1 Byte | 0=>OK, Others=>Error |

5.2.14 Sub-FC41(0x29): Get IR Sensing Record Data

▼ Table 5-33: FC100-Sub-FC41 Request

| Byte order | Description | Size | Value |
|------------|-------------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x29 |
| 03 | Number of records | 1 Byte | 1 ~ 31, read number of records. The size of 1 record is 8 bytes. |

▼ Table 5-34: FC100-Sub-FC41 Response

| Byte order | Description | Size | Value |
|-----------------------------|-----------------|-----------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x29 |
| 03 | Result | 1 Byte | 0=>OK, Others=>Error |
| 04 | Data byte count | 1 Byte | 8 ~ 248, i.e., 8 * N (bytes) where N = 1 ~ 31 |
| 05 ~ [5 + (8*N-1)] | Record data | 8*N bytes | [Year_MSB_1][Year_LSB_1][Month_1][Day_1] [Hour_1][Min_1][Sec_1][Reserved_1] ... [Year_MSB_N][Year_LSB_N][Month_N][Day_N] [Hour_N][Min_N][Sec_N] [Reserved_N] where N=1~31 and data length=8*N bytes |

Note: Data length of 1 record is 8 bytes

([Year_MSB][Year_LSB][Month][Day][Hour][Minute][Second])

5.2.15 Sub-FC42(0x2A): Get IR Sensing Record Mode

▼ Table 5-35: FC100-Sub-FC42 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2A |

▼ Table 5-36: FC100-Sub-FC42 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2A |
| 03 | Record mode | 1 Byte | The way of storing records when storage full: 0=> (default) Clear all records and store from start. 1=> Discard new data and keep 1600 records of old data. |

5.2.16 Sub-FC43(0x2B): Set IR Sensing Record Mode

▼ Table 5-37: FC100-Sub-FC43 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2B |
| 03 | Record mode | 1 Byte | The way of storing records when storage full: 0=> (default) Clear all records and store from start. 1=> Discard new data and keep 1600 records of old data. |

▼ Table 5-38: FC100-Sub-FC43 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|--------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2B |
| 03 | Result | 1 Byte | 0x00=>OK, 0xFF=>Error |

5.2.17 Sub-FC44(0x2C): Get Inverted Red/Blue LED Status

▼ Table 5-39: FC100-Sub-FC44 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2C |

▼ Table 5-40: FC100-Sub-FC44 Response

| Byte order | Description | Size | Value |
|------------|-----------------------------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2C |
| 03 | Inverted Red/Blue LED State | 1 Byte | 0 => default Red(Standby) / Blue(Sensing); 1 => Red(Sensing) / Blue(Standby) |

5.2.18 Sub-FC45(0x2D): Set Inverted Red/Blue LED Status

▼ Table 5-41: FC100-Sub-FC45 Request

| Byte order | Description | Size | Value |
|------------|-----------------------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2D |
| 03 | Inverted Red/Blue LED State | 1 Byte | 0 => default Red(Standby) / Blue(Sensing); 1 => Red(Sensing) / Blue(Standby) |

▼ Table 5-42: FC100-Sub-FC45 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-----------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2D |
| 03 | Result | 1 Byte | 0x00 => OK 0xFF => Error |

5.2.19 Sub-FC46(0x2E): Get Relay Hold Time

▼ Table 5-43: FC100-Sub-FC46 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2E |

▼ Table 5-44: FC100-Sub-FC46 Response

| Byte order | Description | Size | Value |
|------------|---------------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2E |
| 03 | Relay hold time MSB | 1 Byte | High byte of relay hold time (500~20,000ms) e.g. 0x03 0f 0x03E8 (1,000 ms) |
| 04 | Relay hold time LSB | 1 Byte | Low byte of relay hold time (500~20000ms) e.g. 0xE8 of 0x03E8 (1,000 ms) |

5.2.20 Sub-FC47(0x2F): Set Relay Hold Time

▼ Table 5-45: FC100-Sub-FC47 Request

| Byte order | Description | Size | Value |
|------------|---------------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2F |
| 03 | Relay hold time MSB | 1 Byte | High byte of relay hold time (500~20,000ms) e.g. 0x03 of 0x03E8 (1,000 ms) |
| 04 | Relay hold time LSB | 1 Byte | Low byte of relay hold time (500~20000ms) e.g. 0xE8 of 0x03E8 (1,000 ms) |

▼ Table 5-46: FC100-Sub-FC47 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-----------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x2F |
| 03 | Result | 1 Byte | 0x00 => OK 0xFF => Error |

5.2.21 Sub-FC64(0x40): Get Locked Mode

▼ Table 5-47: FC100-Sub-FC64 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x40 |

▼ Table 5-48: FC100-Sub-FC64 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x40 |
| 03 | Locked mode | 1 Byte | 0x00 => disabled (unlocked) 0x01 => enabled (locked) |

5.2.22 Sub-FC65(0x41): Set Locked Mode

▼ Table 5-49: FC100-Sub-FC65 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x41 |
| 03 | Locked mode | 1 Byte | 0x00 => disabled (unlocked) 0x01 => enabled (locked) |

▼ Table 5-50: FC100-Sub-FC65 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-------------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x41 |
| 03 | Result | 1 Byte | 0x00 => OK Others => Error |

5.2.23 Sub-FC66(0x42): Get Day Mode of Locked Periods

▼ Table 5-51: FC100-Sub-FC66 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x42 |

▼ Table 5-52: FC100-Sub-FC66 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x42 |
| 03 | Reserved | 1 Byte | 0x00 |
| 04 | Day mode | 1 Byte | 0x00 => Every day mode (default) 0x01 => Weekday mode |

5.2.24 Sub-FC67(0x43): Set Day Mode of Locked Periods

▼ Table 5-53: FC100-Sub-FC67 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x43 |
| 03 | Day mode | 1 Byte | 0x00 => Every day mode (default) 0x01 => Weekday mode |

▼ Table 5-54: FC100-Sub-FC67 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-----------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x43 |
| 03 | Result | 1 Byte | 0x00 => OK 0xFF => Error |

5.2.25 Sub-FC68(0x44): Get Enabled State of Locked Periods

This command gets the enable/disable status of the 8 locked periods in a day by one byte with 8 bits (b7~b0=>P8~P1) where bit value = 1 means enabled and bit value = 0 disabled. E.g. 0x73 (hex) = 0111 0011 (binary) means 5 locked periods are enabled.

▼ Table 5-55: FC100-Sub-FC68 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x44 |

▼ Table 5-56: FC100-Sub-FC68 Response

| Byte order | Description | Size | Value |
|------------|-------------------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x44 |
| 03 | Reserved | 1 Byte | 0x00 |
| 04 | Every day enabled state | 1 Byte | 0x00 => Every day mode (default) 0x01 => Weekday mode |
| 05 | Reserved | 1 Byte | 0x00 |
| 06 | Sunday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 07 | Reserved | 1 Byte | 0x00 |
| 08 | Monday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 09 | Reserved | 1 Byte | 0x00 |
| 10 | Tuesday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 11 | Reserved | 1 Byte | 0x00 |
| 12 | Wednesday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 13 | Reserved | 1 Byte | 0x00 |
| 14 | Thursday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 15 | Reserved | 1 Byte | 0x00 |
| 16 | Friday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 17 | Reserved | 1 Byte | 0x00 |
| 18 | Saturday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |

5.2.26 Sub-FC69(0x45): Set Enabled State of Locked Periods

This command gets the enable/disable status of the 8 locked periods in a day by one byte with 8 bits (b7~b0=>P8~P1) where bit value = 1 means enabled and bit value = 0 disabled. E.g. 0x73 (hex) = 0111 0011 (binary) means 5 locked periods are enabled.

▼ Table 5-57: FC100-Sub-FC69 Request

| Byte order | Description | Size | Value |
|------------|-------------------------|--------|--|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x45 |
| 03 | Reserved | 1 Byte | 0x00 |
| 04 | Every day enabled state | 1 Byte | 0x00 => Every day mode (default) 0x01 => Weekday mode |
| 05 | Reserved | 1 Byte | 0x00 |
| 06 | Sunday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 07 | Reserved | 1 Byte | 0x00 |
| 08 | Monday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 09 | Reserved | 1 Byte | 0x00 |
| 10 | Tuesday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 11 | Reserved | 1 Byte | 0x00 |
| 12 | Wednesday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 13 | Reserved | 1 Byte | 0x00 |
| 14 | Thursday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 15 | Reserved | 1 Byte | 0x00 |
| 16 | Friday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 17 | Reserved | 1 Byte | 0x00 |
| 18 | Saturday enabled state | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |

▼ Table 5-58: FC100-Sub-FC69 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-----------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x45 |
| 03 | Result | 1 Byte | 0x00 => OK 0xFF => Error |

5.2.27 Sub-FC70(0x46): Get 8 Locked Periods

This command gets 8 locked periods in a day from module. One locked period composed of Start Time and End Time. The End Time should be late after the Start Time.

▼ Table 5-59: FC100-Sub-FC70 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x46 |

▼ Table 5-60: FC100-Sub-FC70 Response

| Byte order | Description | Size | Value |
|------------|-----------------|----------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x46 |
| 03 | P1 Start Hour | 1 Byte | 0 ~ 23, period 1 start Hour |
| 04 | P1 Start Minute | 1 Byte | 0 ~ 59, period 1 start Minute |
| 05 | P1 Start Second | 1 Byte | 0 ~ 59, period 1 start second |
| 06 | P1 End Hour | 1 Byte | 0 ~ 23, period 1 end Hour |
| 07 | P1 End Minute | 1 Byte | 0 ~ 59, period 1 end Minute |
| 08 | P1 End Second | 1 Byte | 0 ~ 59, period 1 end second |
| 09~44 | P2 to P7 ... | 36 Bytes | period 2 ~ 7 start time and end time |
| 45 | P8 Start Hour | 1 Byte | 0x00 |
| 46 | P8 Start Minute | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 47 | P8 Start Second | 1 Byte | 0x00 |
| 48 | P8 End Hour | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 49 | P8 End Minute | 1 Byte | 0x00 |
| 50 | P8 End Second | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |

5.2.28 Sub-FC71(0x47): Set 8 Locked Periods

This command sets 8 locked periods in a day to module. One locked period composed of Start Time and End Time. **The End Time should be late after the Start Time.**

▼ Table 5-61: FC100-Sub-FC71 Request

| Byte order | Description | Size | Value |
|------------|-----------------|----------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x47 |
| 03 | P1 Start Hour | 1 Byte | 0 ~ 23, period 1 start Hour |
| 04 | P1 Start Minute | 1 Byte | 0 ~ 59, period 1 start Minute |
| 05 | P1 Start Second | 1 Byte | 0 ~ 59, period 1 start second |
| 06 | P1 End Hour | 1 Byte | 0 ~ 23, period 1 end Hour |
| 07 | P1 End Minute | 1 Byte | 0 ~ 59, period 1 end Minute |
| 08 | P1 End Second | 1 Byte | 0 ~ 59, period 1 end second |
| 09~44 | P2 to P7 ... | 36 Bytes | period 2 ~ 7 start time and end time |
| 45 | P8 Start Hour | 1 Byte | 0x00 |
| 46 | P8 Start Minute | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 47 | P8 Start Second | 1 Byte | 0x00 |
| 48 | P8 End Hour | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |
| 49 | P8 End Minute | 1 Byte | 0x00 |
| 50 | P8 End Second | 1 Byte | 0x00 ~ 0xFF, enabled state of 8 periods |

▼ Table 5-62: FC100-Sub-FC71 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x47 |
| 03 | Result | 1 Byte | 0x00 => OK Others => Error, bit0~bit7 correspond to period1~period8. Bit value=1 means invalid settings. |

5.2.29 Sub-FC72(0x48): Get Enabled State of Locked Period Function

▼ Table 5-63: FC100-Sub-FC72 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x48 |

▼ Table 5-64: FC100-Sub-FC72 Response

| Byte order | Description | Size | Value |
|------------|---------------|--------|-------------------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x48 |
| 03 | Enabled state | 1 Byte | 0x00 => disabled 0x01 => enabled |

5.2.30 Sub-FC73(0x49): Set Enabled State of Locked Period Function

Note: Settings of Sub-FC66~ 71 are effective when this function is enabled.

▼ Table 5-65: FC100-Sub-FC73 Request

| Byte order | Description | Size | Value |
|------------|---------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x49 |
| 03 | Enabled state | 1 Byte | 0x00 => disabled (default) 0x01 => enabled |

▼ Table 5-66: FC100-Sub-FC73 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-----------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x49 |
| 03 | Result | 1 Byte | 0x00 => OK 0xFF => Error |

5.2.31 Sub-FC76(0x4C): Get Scale Value of Rotary Switch

Note: Settings of Sub-FC66~ 71 are effective when this function is enabled.

▼ Table 5-67: FC100-Sub-FC76 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x4C |

▼ Table 5-68: FC100-Sub-FC76 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x4C |
| 03 | Scale value | 1 Byte | 0x00 ~ 0x0F |

5.2.32 Sub-FC77(0x4D): Get Toggle Mode

▼ Table 5-69: FC100-Sub-FC77 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x4D |

▼ Table 5-70: FC100-Sub-FC77 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x4D |
| 03 | Toggle mode | 1 Byte | 0x00 => disabled (default) 0x01 => enabled |

5.2.33 Sub-FC78(0x4E): Set Toggle Mode

▼ Table 5-71: FC100-Sub-FC78 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|---|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x4E |
| 03 | Toggle mode | 1 Byte | 0x00 => disabled (default) 0x01 => enabled |

▼ Table 5-72: FC100-Sub-FC78 Response

| Byte order | Description | Size | Value |
|------------|-------------|--------|-----------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0x49 |
| 03 | Result | 1 Byte | 0x00 => OK 0xFF => Error |

5.2.34 Sub-FC165(0xA5): Reboot Module

▼ Table 5-73: FC100-Sub-FC165 Request

| Byte order | Description | Size | Value |
|------------|-------------|--------|------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0xA5 |

▼ Table 5-74: FC100-Sub-FC165 Response

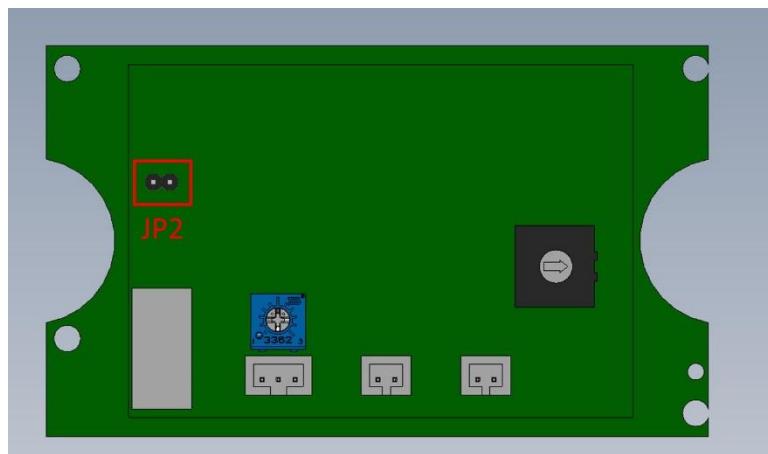
| Byte order | Description | Size | Value |
|------------|-------------|--------|-------------------------------|
| 00 | Address | 1 Byte | 1 ~ 247 (Net ID) |
| 01 | FC | 1 Byte | 0x64 |
| 02 | Sub-FC | 1 Byte | 0xA5 |
| 03 | Result | 1 Byte | 0x00 => OK Others => Error |

Appendix A. Update Firmware

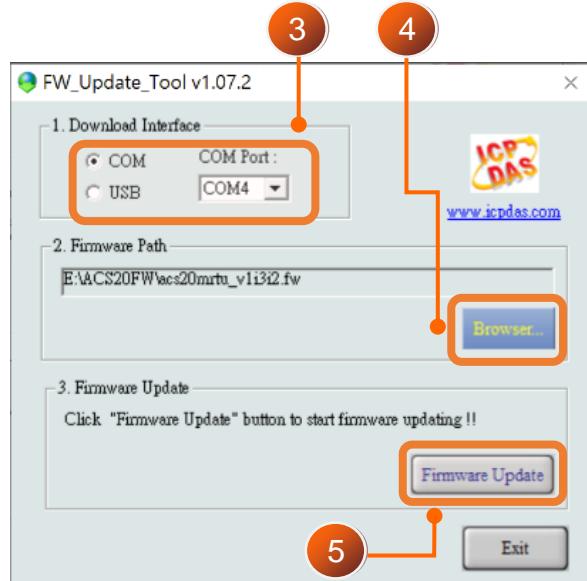
To update the firmware, users can click the menu [Tool] -> [Firmware Update Tool] from the ACS-20-MRTU Utility to launch the firmware update tool (must be v1.07.2). Please follow the below steps to finish the update firmware procedure, which is also depicted in Figure A-1.

- (1) Power off the module. Release the back case.
- (2) Short the two pins of JP2 and then power on the module. Red & blue LED blink 2 times per second which means it is in firmware update mode.
- (3) Click “COM” radio button and select “COM Port” connected to ACS-20B(W)-MRTU..
- (4) Click “Browser” to find the firmware file, e.g., acs20mrtu_v#i#i#.fw.
- (5) Click “Firmware Update” button to start the update procedure.
- (6) After firmware update finished, power cycle the module. Click Utility Menu [About] to check the firmware version.

Note: The all configuration settings would not be changed except RTC time after firmware update.



▲ Figure A-1: JP2 position.



▲ Figure A-2: Firmware update procedure.

The firmware of ACS-20B(W)-MRTU can be downloaded from:

<https://www.icpdas.com/en/download/index.php?model=ACS-20B-MRTU>

Appendix B. Revision History

This chapter provides revision history information to this document.

▼ Table B-1: Revision History

| Version | Date | Description of changes |
|---------|-----------|--|
| 1.0 | 2021-1-24 | The First Release Revision |
| 1.1 | 2021-2-3 | 1. Add section 4.8. 2. Update section 5.2.15 & 5.2.16. 3. Update appendix A. |
| 1.2 | 2022-3-08 | 1. Correct errors. 2. Add Modbus holding register table and Coil table in chapter 5.. |
| 1.3 | 2022-3-22 | 1. Modify the figure of utility. |
| 1.4 | 2023-1-11 | 1. Add section 5.1.4 for Modbus Discrete Inputs. |