

PISO/PEX-CM100 Quick Start

Packing List

In addition to this guide, the package includes the following items:







Quick Start

Technical Support

service@icpdas.com www.icpdas.com

Resources

How to search for drivers, manuals and spec information on ICP DAS website.

• For Mobile Web



1. Jump, Switch and Pin Assignment

Jump and Switch:

	PISO-CM100U Rev 1.xx	PISO-CM100U Rev 2.xx	PEX-CM100
Debug Port	JP2	JP4	JP4
Flash Protect	JP3	JP3	JP3
Terminal Resistance	JP4	JP5	JP5
Reset Button	SW2	SW2	SW2
Board Switch	SW1	SW1	SW1

Terminal Resistance (120 Ω)	Board Switch (0	~ 15)
Enable Disable	DIP switch ON 1 2 3 4	Be careful, the board No. of each CM100s, DNM100s and CPM100s in your PC nust be unique.

Pin Assignment:



5-pin Screw Terminal



9-pin D-sub Male

Pin	Signal	Description
1	CAN_GND	Ground
2	CAN_H	CAN_H bus line
3	CAN_SHLD	Optional CAN Shield
4	CAN_L	CAN_L bus line
5	N/A	No use

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1	N/A	No use
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4	N/A	No use
5	CAN_SHLD	Optional CAN Shield
6	CAN_GND	Ground
7	CAN_H	CAN_H bus line
8	N/A	No use
9	N/A	No use

2. Installing Windows Driver

Step1. Setup the Windows driver. The driver is located at: <u>Web:</u>



Step2. The default driver installation path is C:\ICPDAS\PISO-CM100. Please follow the installation process prompts and click the "Next" button to complete the installation °

For more detailed installation instructions, please refer to the user manual, the user manual path: Web:



3. Installing PISO / PEX-CM100 CAN Board Step1. Shut down and power off your

PC, then remove its' case.

Step2. Select a suitable slot and insert the CAN card into the slot.

Step3. Replace the PC case and power on the computer. Step4. After the boot is complete,

please follow the prompts to

complete the driver installation.



* PISO-CM100U is PCI slot PEX-CM100 is PCIe X1 slot

4. Wiring and testing



- Step1. Connect the CAN port of the CAN board to the customer's CAN device and power on.
- Step2. Open CANUtility.exe located in C:\ICPDAS\PISO-CM100.
- Step3. Select the proper CAN card and baud rate and press OK.
- Step4. Add the command that the device can receive and send it, CANUtility will automatically receive the response message.

