



CAN-2088C PWM module of CANopen Slave

■ Features

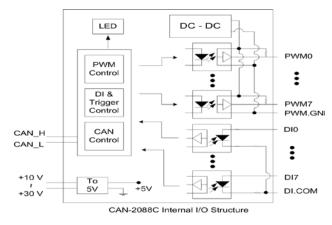
- Hardware-controlled PWM output
- PWM output frequency: 0.2 Hz ~ 500 kHz with 0.1%~99.9% duty cycle
- PWM Output Modes: software trigger / hardware trigger
- Trigger each PWM output individually or all PWM outputs synchronously
- Support Burst output mode and Continue output mode
- Provide 32-bit 500 kHz high-speed counter for each DI channel
- Pass the validation of CANopen conformance test
- Provide EDS file for CANopen master interface



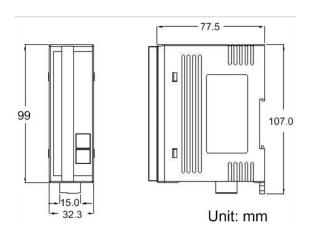
Introduction

PWM (Pulse width modulation) is a powerful technique for controlling analog circuits. By using digital outputs, it can generate a waveform with variant duty cycle and frequency to control analog circuits. CAN-2088C, a CAN bus remote I/O module with CANopen protocol, provides 8 PWM output channels and 8 digital inputs channels with high-speed counter function. It can be used to develop practical and economical analog control systems in the CANopen network.

Internal I/O Structure



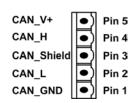
Dimensions



I/O Pin & Wire Connection

Terminal No.	. Pin Assignment	Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0
[o 0	1 PO.0	Drive Relay	Relay On	Relay Off
[o] 02	2 PO.1			
[0	3 PO.2		PO X PO.GND	PO X PO.GND
[o] 04	4 PO.3		- LIGHT FO.GND	+ DO FORM
[o] 08	5 PO.4	2 1000		
∑ ∘ ⟨ 0€	6 PO.5	Resistance Load	†di pox	**************************************
[0	7 PO.6		PO.GND	□ PO.GND
[○ (00	8 PO.7		ON State LED ON	OFF State LED OFF
[○] 09	9 PO.GND	Input Type	Readback as 1	Readback as 0
o (1	PO.GND	Delevi	Relay On	Relay Off
ু ি 1	1 DI.0	Relay Contact	+ □⊝ DIX	+ □ DIX
[o { 12	2 DI.1		Relay Close DI.GND	Relay Open DI.GND
[□ (1	3 DI.2	TTL/CMOS	Voltage > 10 V	Voltage < 4 V
[o] 1	4 DI.3	Logic	Logic Power DI X	Logic Power Copic Level Low DI X DI GND
[o] 1	5 DI.4		Open Collector On	Open Collector Off
[o { 16	6 DI.5	NPN	. +	. 4
[_0] 1	7 DI.6	Output	DI X DI.GND	DIX D⊝ DIGND
[18	B DI.7		Open Collector On	Open Collector Off
[19	9 DI.GND	PNP Output	xiall@ah:	XIQ I DOLX
[0 20	DI.GND	Output	ON \$ DI.GND	OFFE □ DI.GND

CAN Pin & Baud Rate Rotary





rotar

PROOF	0	10 kbps
	1	20 kbps
0 St & V	2	50 kbps
	3	125 kbps
	4	250 kbps
ud rate	5	500 kbps
y switch	6	800 kbps
	7	1000 kbps

Switch Value

Baud Rate

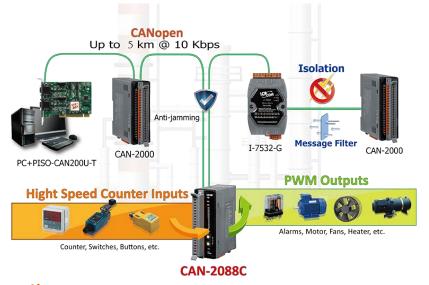
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Specifications

Specifications			
CAN Interface			
Connector	5-pin screwed terminal block (CAN_GND, CAN_L, CAN_SHLD, CAN_H, CAN_V+)		
Baud Rate (bps)	10 k, 20 k, 50 k, 125 k, 250 k, 500 k, 800 k, 1M		
Terminal Resistor	Switch for 120 Ω terminal resistor		
Node ID	1~99 selected by rotary switch		
Protocol	CANopen DS-301 ver4.02, DS-401 ver2.1		
No. of PDOs	10 Rx, 10 Tx (support dynamic PDO)		
PDO Mode	Event Triggered, Remotely requested, Cyclic and acyclic SYNC		
Error Control	Node Guarding protocol and Heartbeat Producer protocol		
Emergency Message	Yes		
PWM Interface			
Channels	8 (Source)		
Output Max. Load	1 mA		
Frequency Range	0.2 Hz ~ 500 kHz (non-continuous, the min. unit of the high/low level signal is 1 us)		
PWM Mode	Continue mode, Burst mode, Hardware trigger mode, Software trigger mode		
ESD Protection	4 kV Contact for each channel		
DI Interface			
Channels	8 (Sink)		
Counter Frequency	32-bit, 500 kHz Max.		
ESD Protection	4 kV Contact for each channel		
LED			
Round LED	PWR LED, RUN LED, ERR LED		
I/O LED	8 LEDs as PWM, 8 LEDs as Digital Input, and 1 LED as terminal resister indicator		
Power			
Input range	Unregulated +10 ~ +30 VDC		
Power Consumption	3.5 W		
Mechanism			
Installation	DIN-Rail		
Dimensions	32.3 mm x 99 mm x 77.5 mm (W x L x H)		
Environment			
Operating Temp.	-25 ~ +75 ℃		
Storage Temp.	-30 ~ +80 ℃		
Humidity	10 ~ 90% RH, non-condensing		

Application



Ordering Information

CAN-2088C	CANopen Module of 8-channel PWM and 8-channel DI with High-speed Counters
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