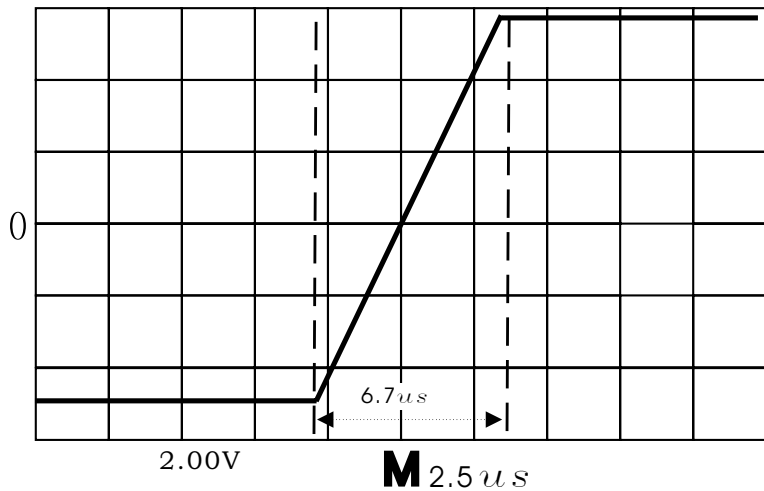
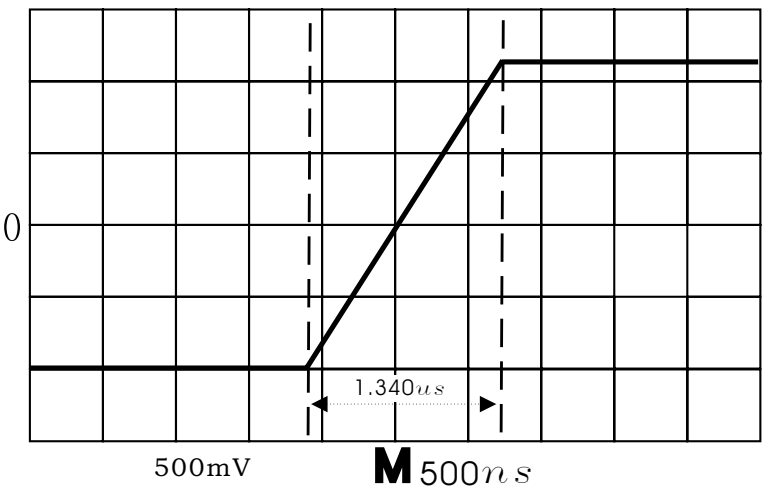


± 10V



± 5V



± 1V

1.CPU=AMD K6-400

2.Windows

3.PIODA16 ; ± 10V Speed=13.40us

4.PIODA16 ; ± 5V Speed=6.70us

5.PIODA16 ; ± 1V Speed=1.340us

D/AOutput

```

{
  For(x=0;x<=3;x++)
  {
    pio_da16_da(0,0x3FFF);delay(1);
    pio_da16_da(0,0x0000);delay(1);
  }
void pio_da16_da(int iChannel_no,int iVal)
{
  iVal=iVal+(iChannel_no)*0x4000;
  outportb(wBase+0xf0,iVal);
  outportb(wBase+0xf4,(iVal>8));
  outportb(wBase+0xe0,0x0ff);
}
}

```

For(x=0;x<=3;x++)

```

{
  pio_da16_da(0,0x0fff);delay(1);
  pio_da16_da(0,0x2fff);delay(1);
}

```

For(x=0;x<=3;x++)

```

{
  pio_da16_da(0,0x1C9F);delay(1);
  pio_da16_da(0,0x2300);delay(1);
}

```